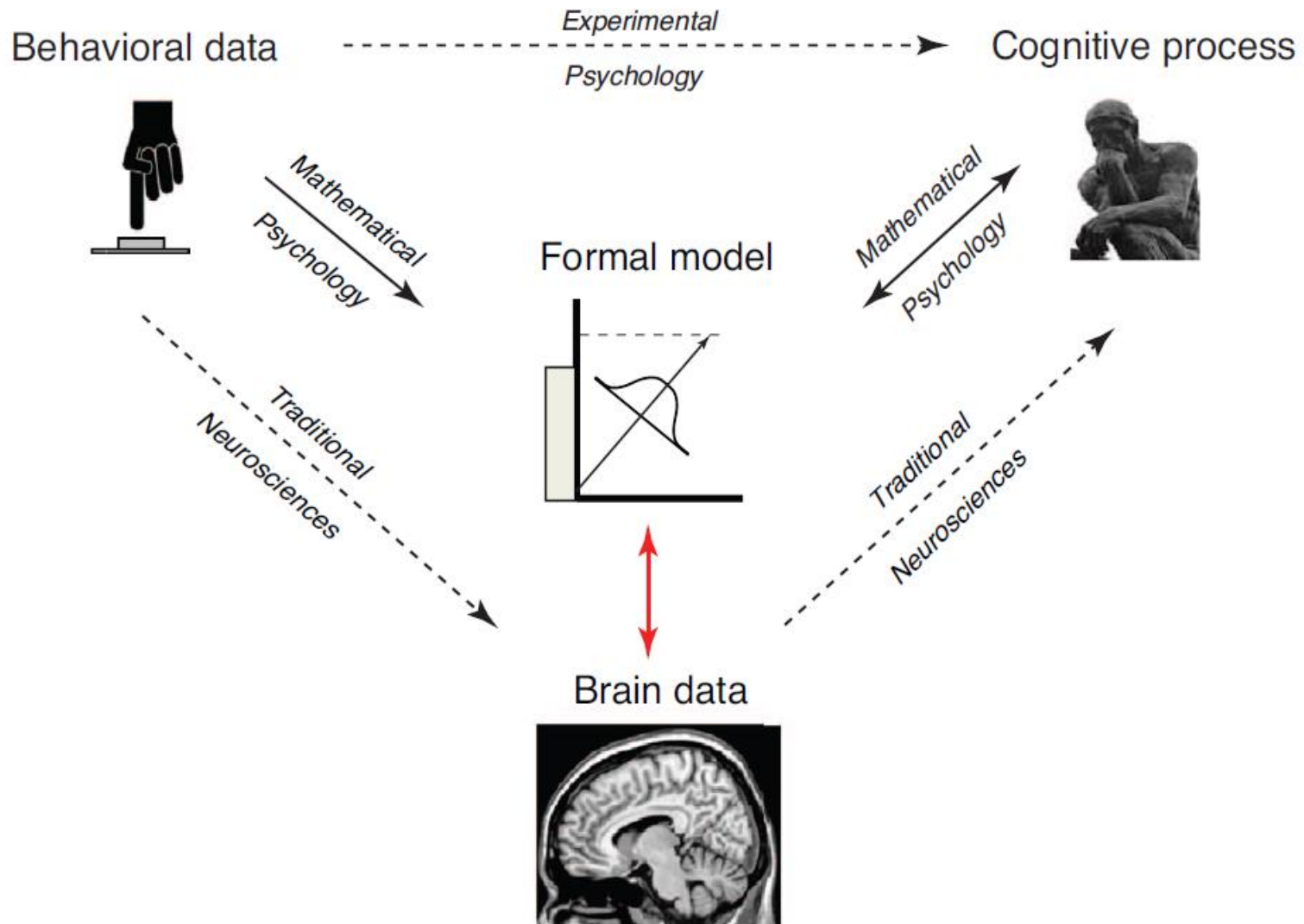


SBI SUMMER SCHOOL: JOINT MODELING



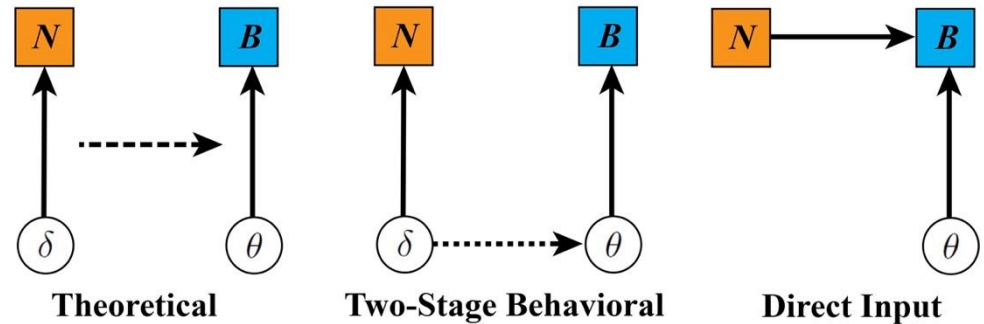
LINKING NEUROSCIENCE TO COGNITIVE MODELS



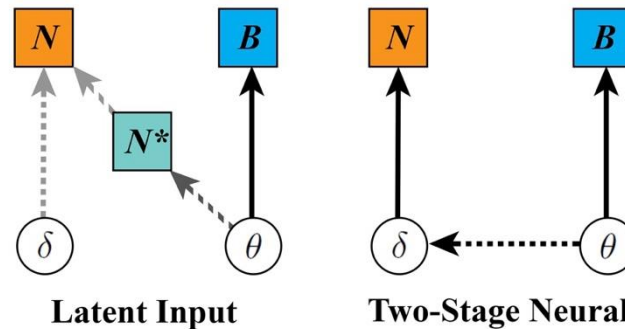
Linking Brain and Behavior

1. Neural data can constrain the behavioral model
2. Behavioral model can predict neural data
3. Model everything at once

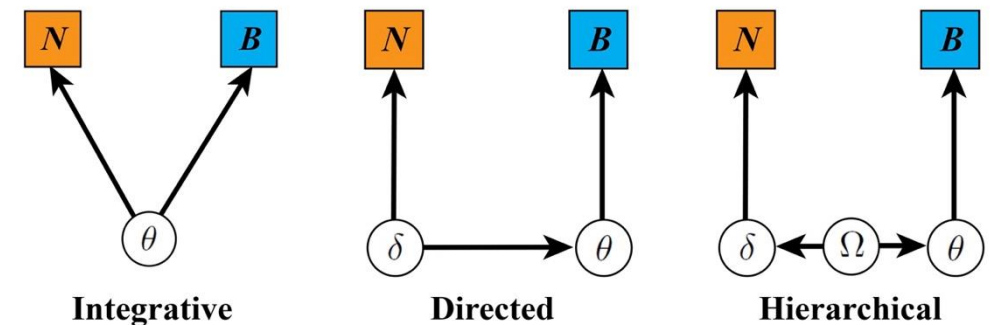
Neural Data Constrain Behavioral Model



Behavioral Model Predicts Neural Data



Joint (Simultaneous) Modeling

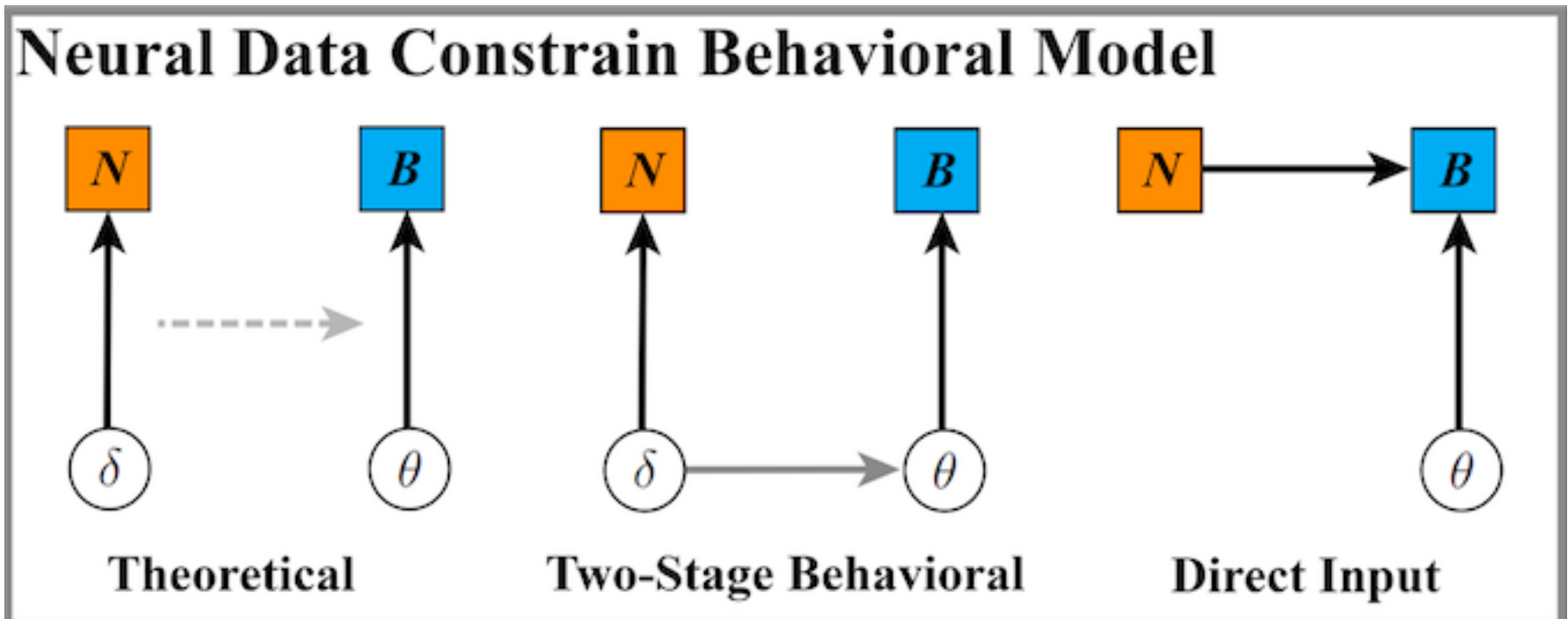


NEURAL DATA CONSTRAIN BEHAVIORAL MODEL

- **In developing models, we have many choices and assumptions to make**
- **Rather than make these arbitrarily, or develop theoretical justification for them, we could look to the implementation level**
- **One prominent approach in MbCN is to use the neural data to constrain the development of the behavioral model**

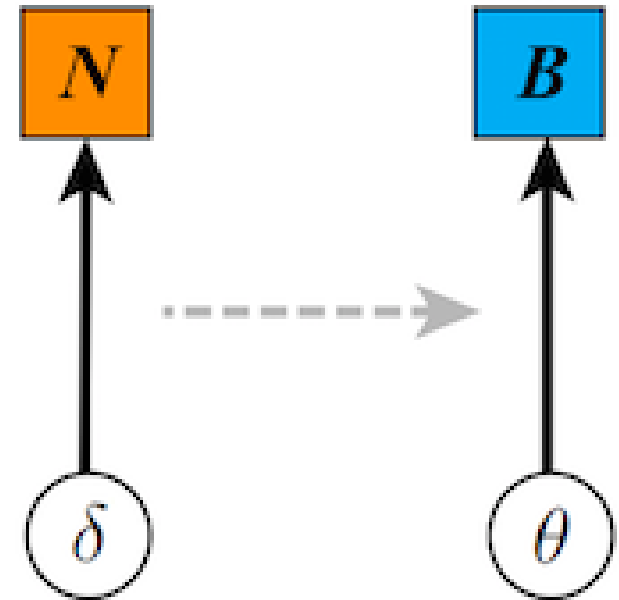
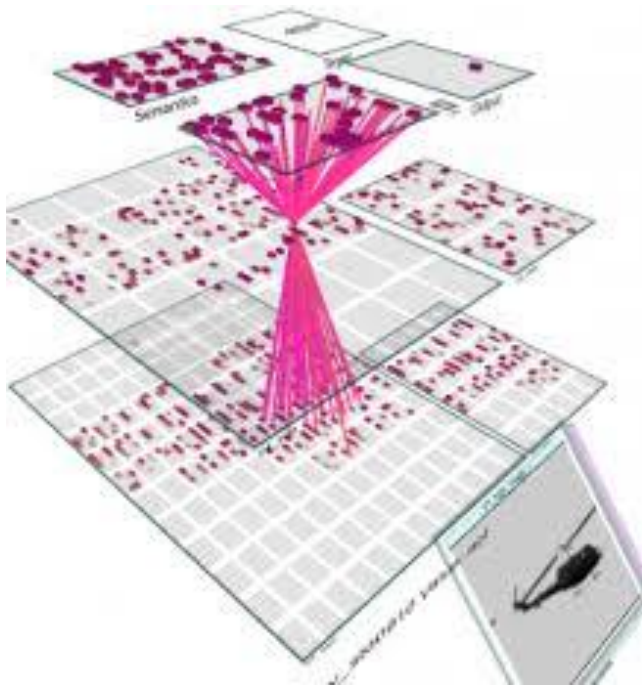
NEURAL DATA CONSTRAIN BEHAVIORAL MODEL

- Here are some examples:



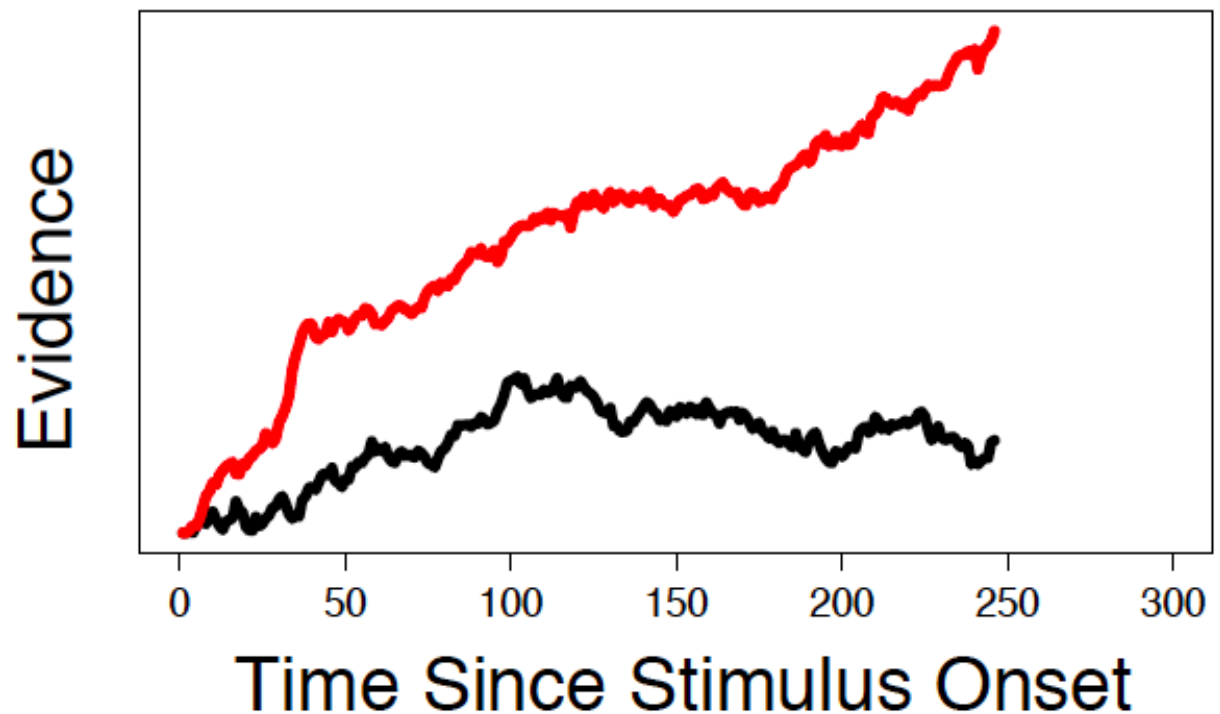
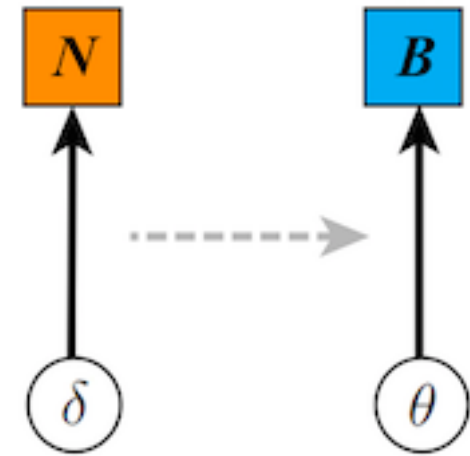
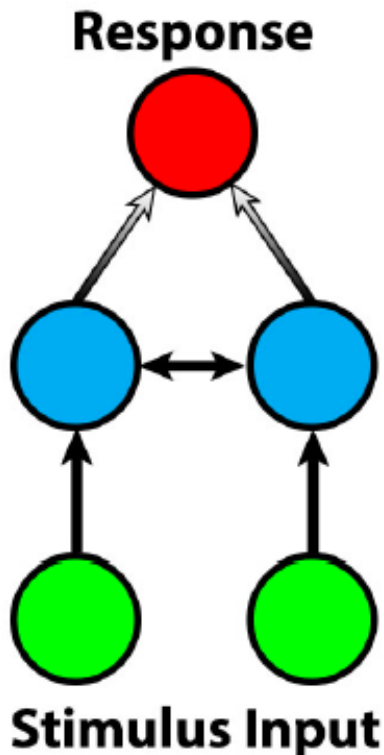
THEORETICAL

- Development of models with neurally-inspired architectures
 - Connectionist frameworks
 - LEABRA
 - LCA



THEORETICAL

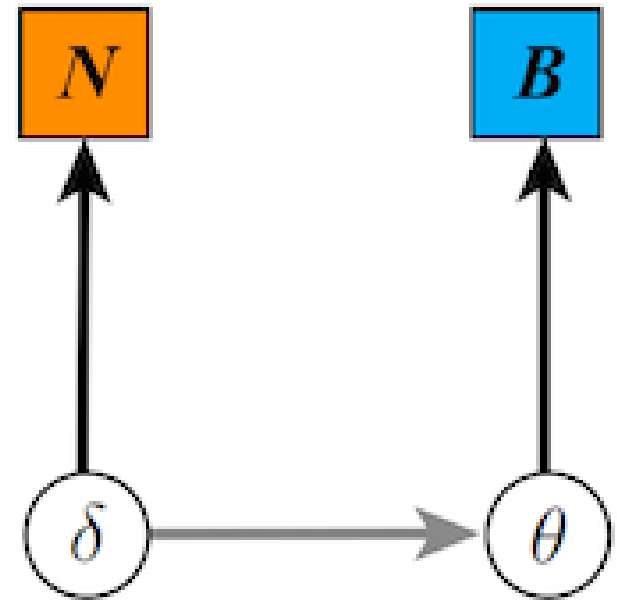
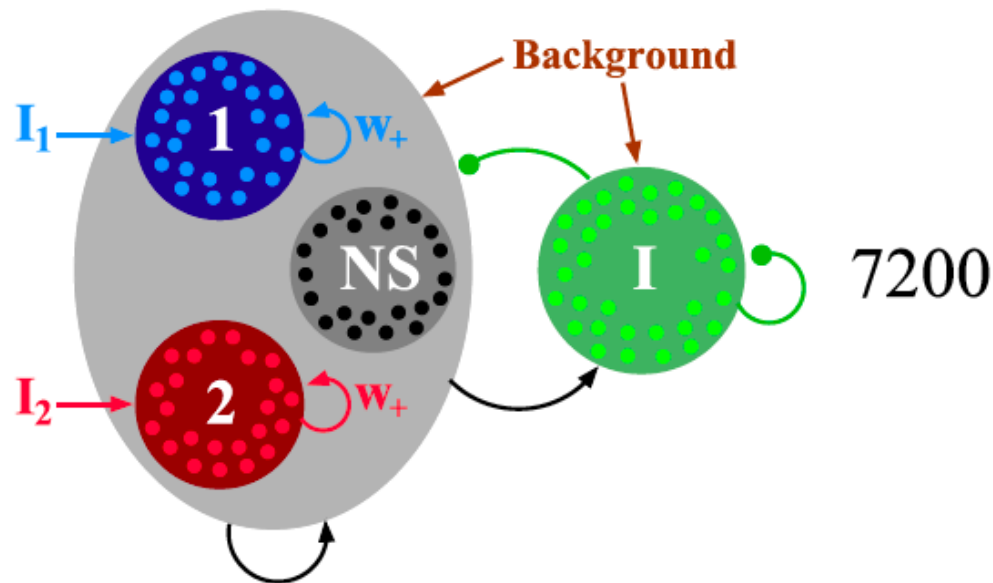
- Development of models with neurally-inspired architectures



TWO-STAGE BEHAVIORAL

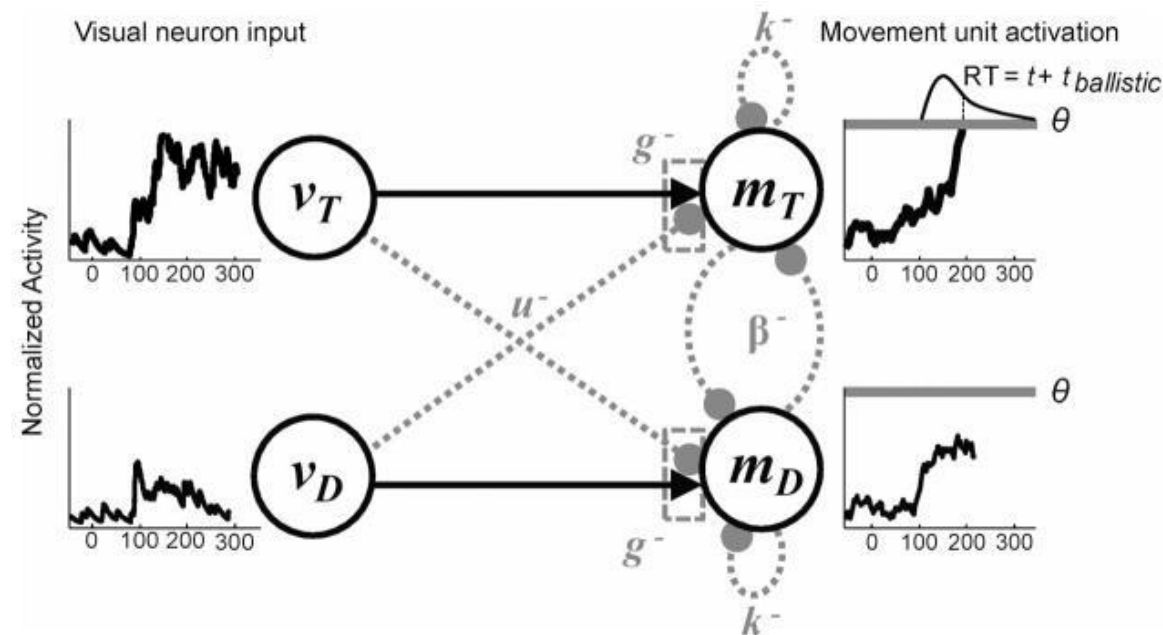
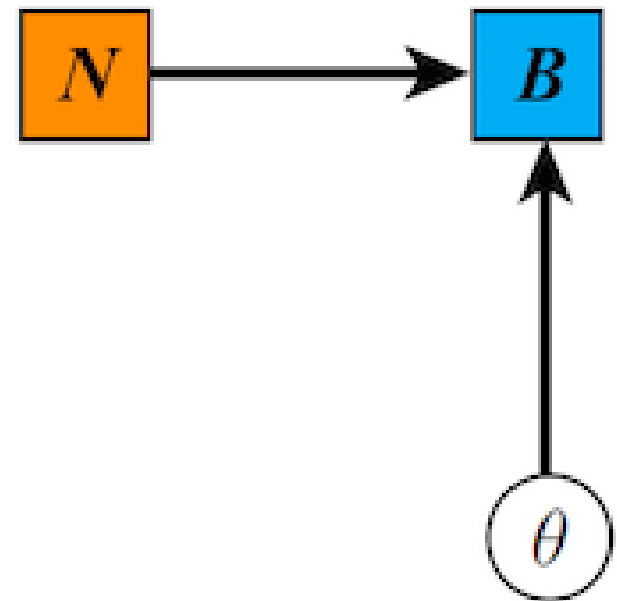
- Using a model to characterize how the implementation level is carried out, then using these parameters to generate predictions for behavioral data

Spiking neuronal network model



DIRECT INPUT

- Type of model that uses neural data – or some transformation of it – to directly inform the model
 - Gated accumulator model



NEURALLY CONSTRAINED MODELING OF PERCEPTUAL DECISION MAKING

- Building off the finding that the dynamics of some neurons resemble an accumulation to threshold process
- “This synthesis is powerful because neurophysiology can constrain key assumptions about the representation of perceptual evidence, the mechanisms that accumulate evidence to threshold, and how the two interact”
- Plan to use neural data to constrain the evidence accumulation process



Tom Palmeri

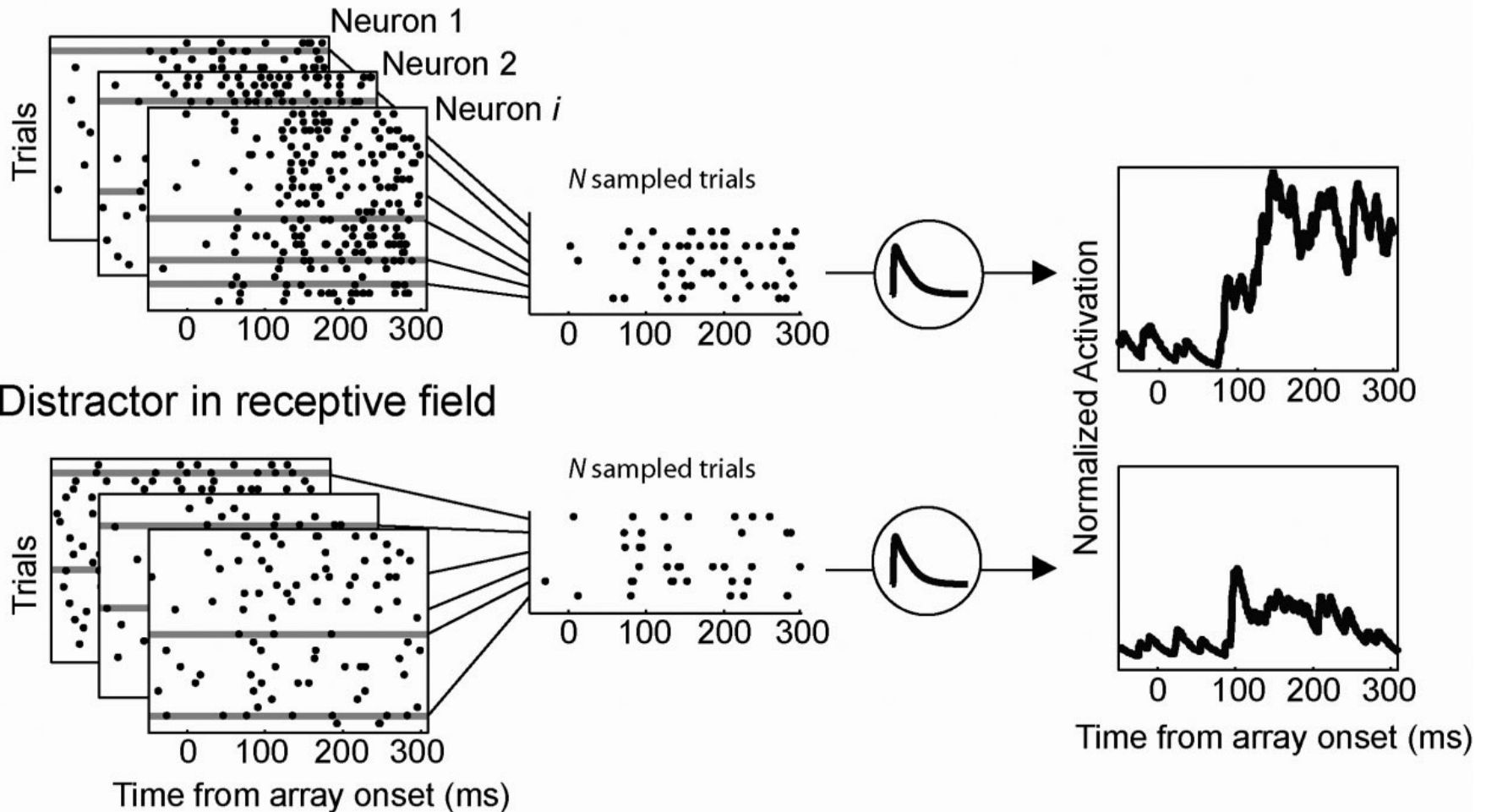


Gordon Logan

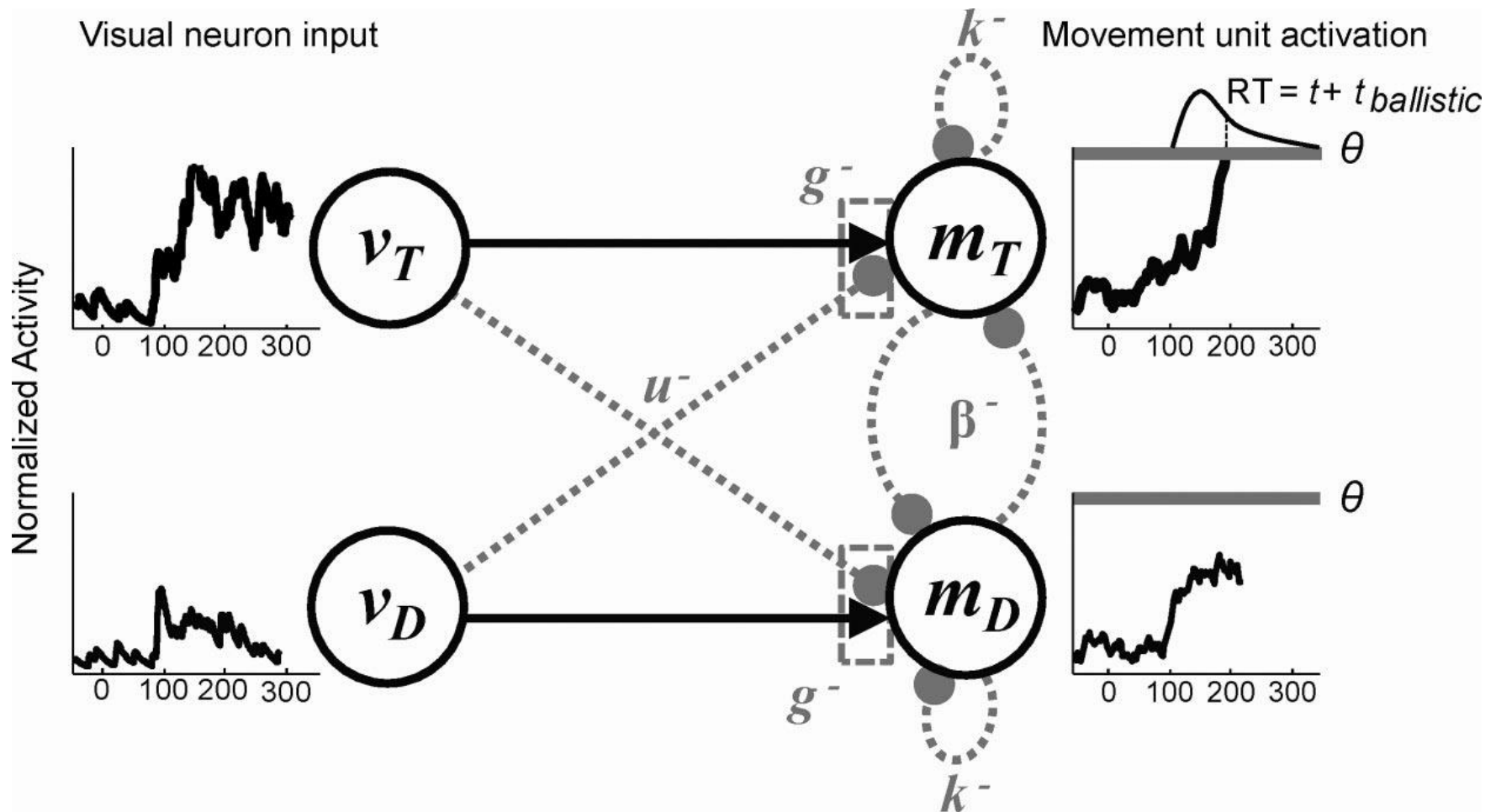


MODELING -- SUMMARY

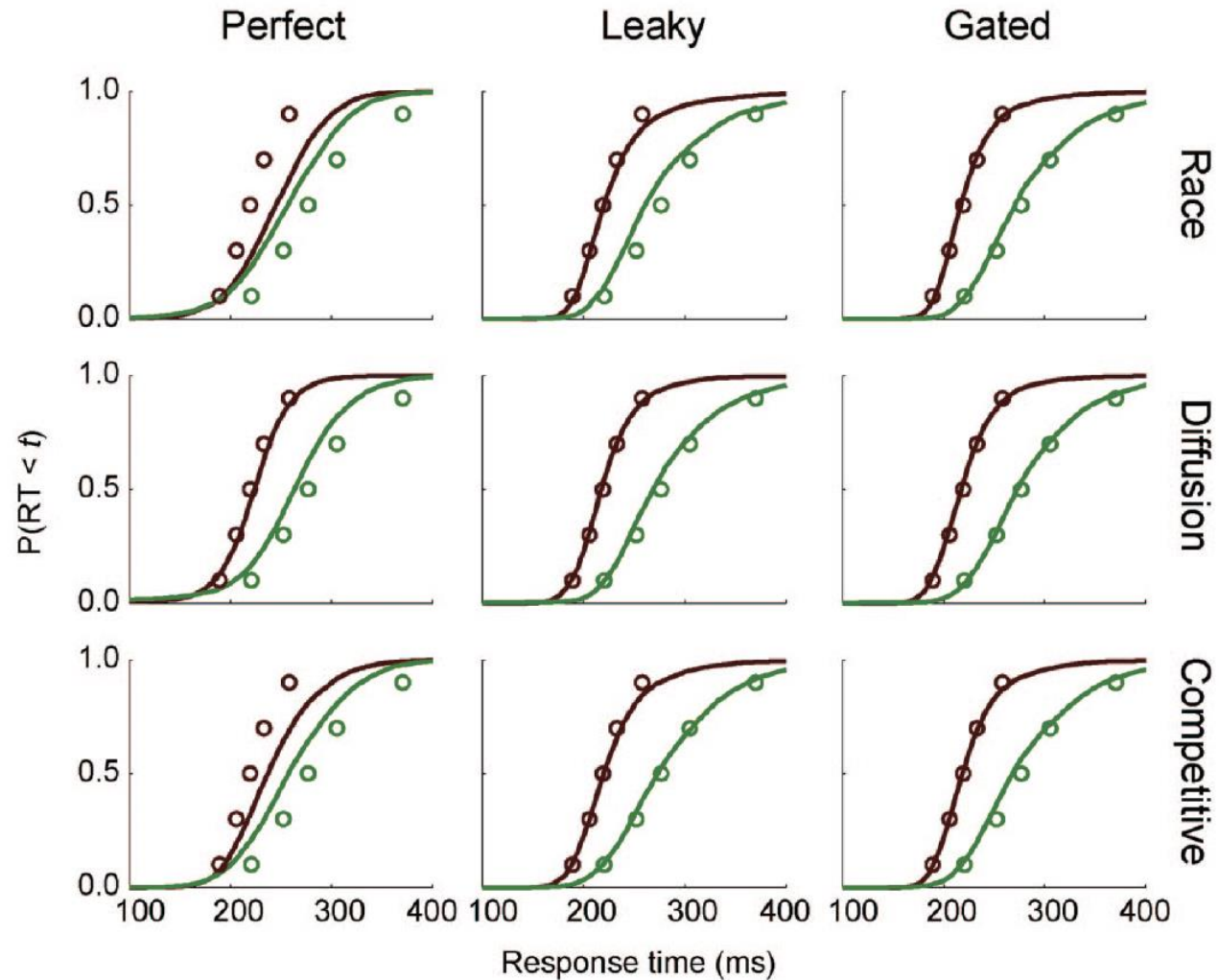
Target in receptive field



MODELING -- SUMMARY



BEHAVIORAL FITS

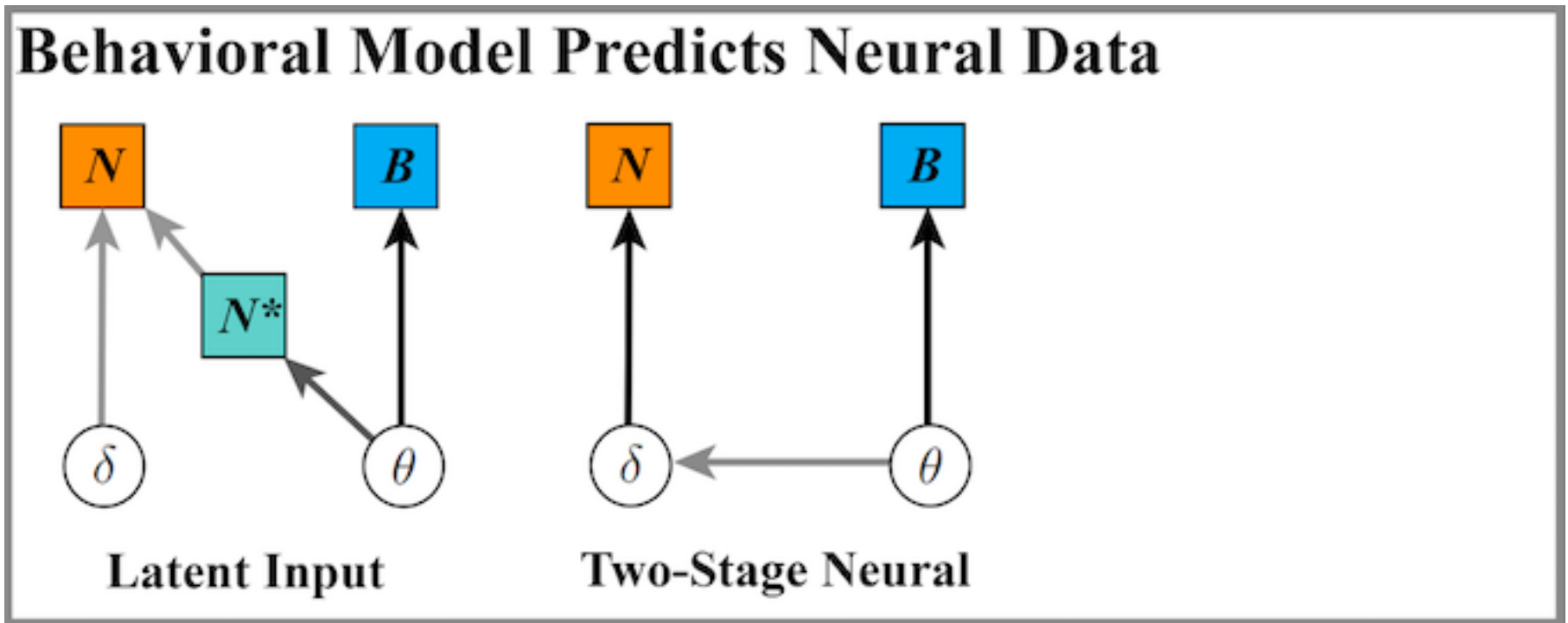


BEHAVIORAL MODEL PREDICTS NEURAL DATA

- **Sometimes we have cognitive models that capture the behavioral data really well**
- **...but may not have any understanding of the neural basis of the mechanisms assumed by the model**
- **Try to use model parameters to guide the search for mechanisms in the brain**

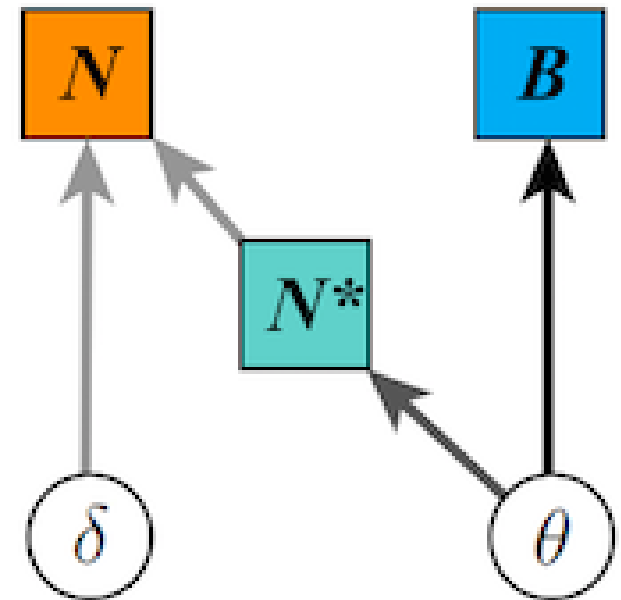
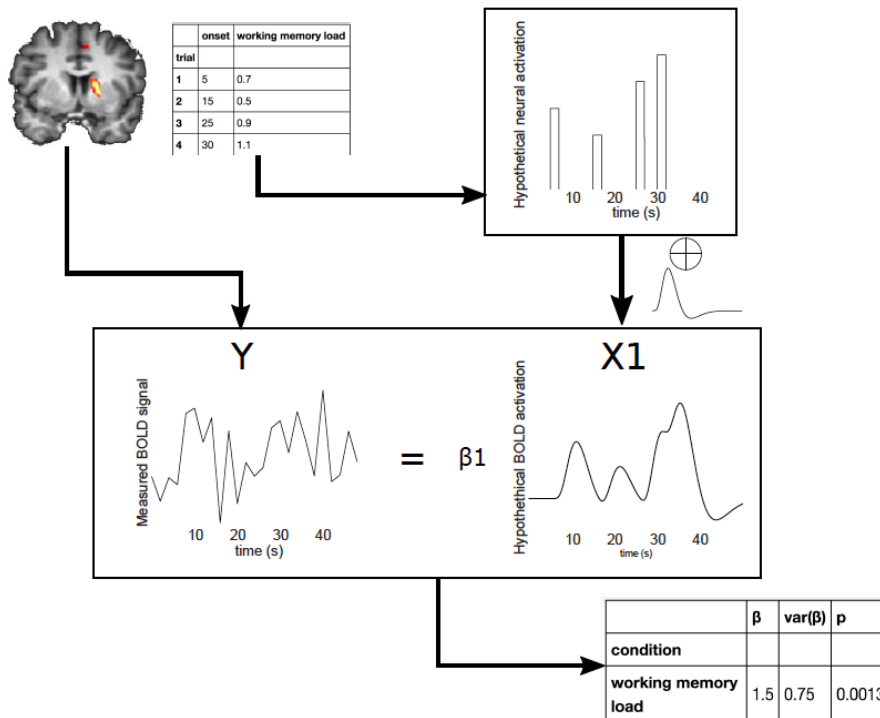
BEHAVIORAL MODEL PREDICTS NEURAL DATA

- Here are some examples:

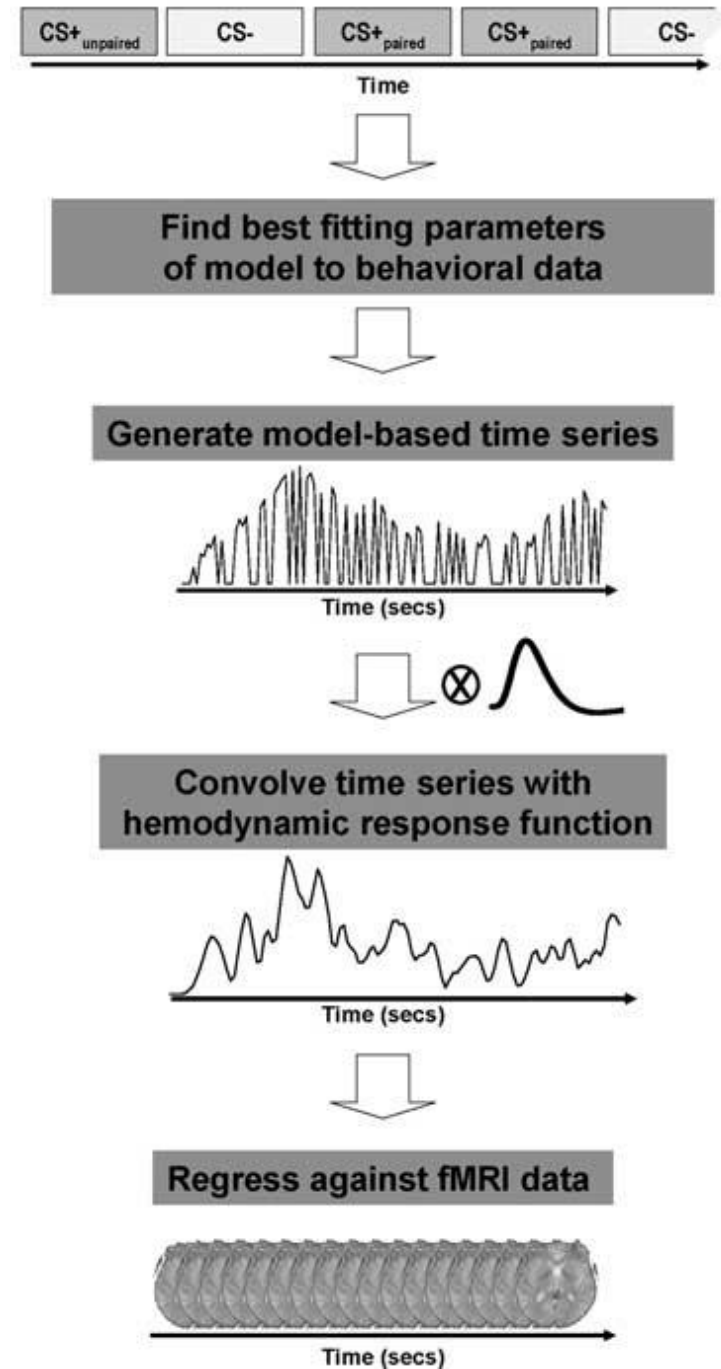


LATENT INPUT

- Use B to estimate behavioral model parameters, which are then used to guide the analysis of the neural data
 - Model-based fMRI



Pass individual subject trial history to model



APPROACH

1. Find the best fitting parameters of model from fitting it to behavioral data
2. Generate model-based time series
3. Convolve the time series with an HRF to form predictions for neural data
4. Correlate the predictions with observed neural responses

APPLICATION

- In uncertain environments, one must consider absorbing resources in a particular area versus moving to a new area for a potentially richer set of rewards
- Explored the exploration/exploitation trade-off in humans on a bandit problem, with time-varying rewards
- Found that the brain codes for values of rewards in very specific areas



Nathaniel Daw

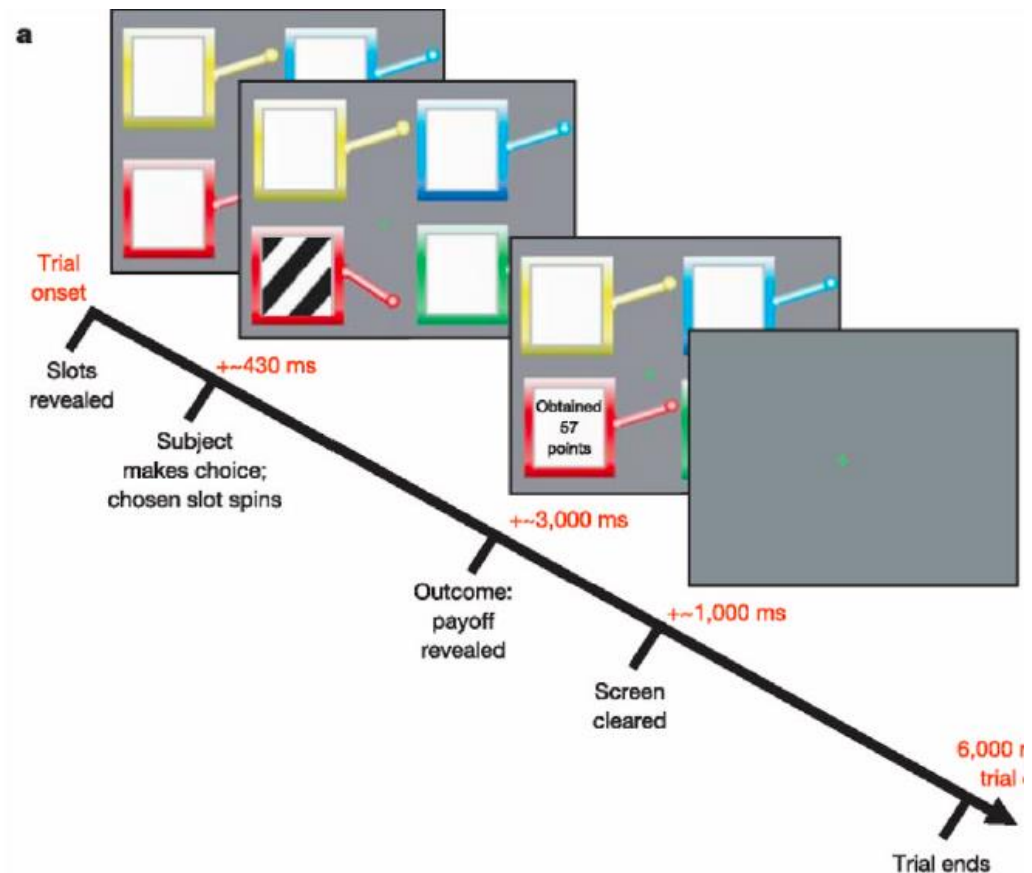


John O'Doherty

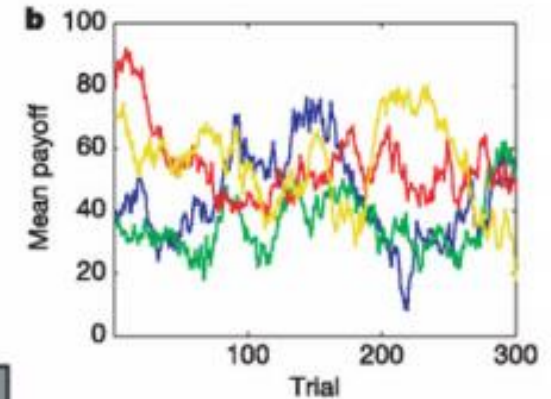
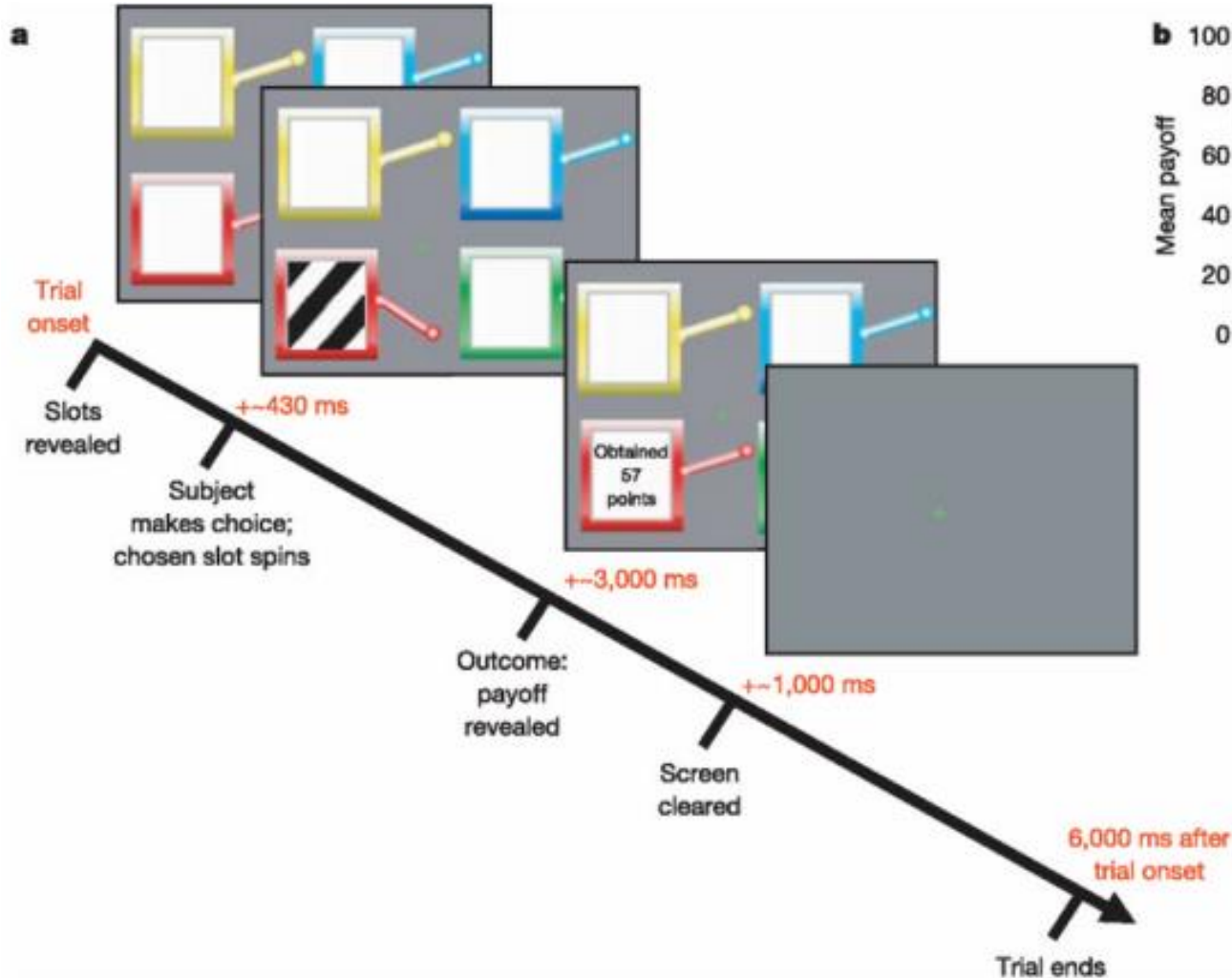
Daw, N., O'Doherty, J.P., Dayan, P., Seymour, B., Dolan, R.J. (2006).
Cortical substrates for exploratory decisions in humans. *Nature*, 441:876-9.

FOUR-ARM BANDIT

- Four options presented
- Choose among them
- Reward given on the basis of choice
- Reward is noisy, varying from one trial to the next



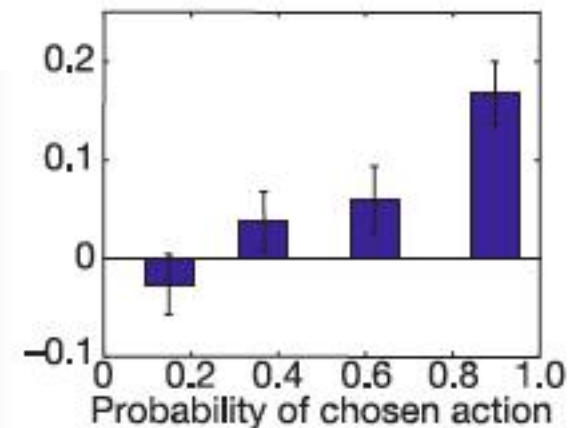
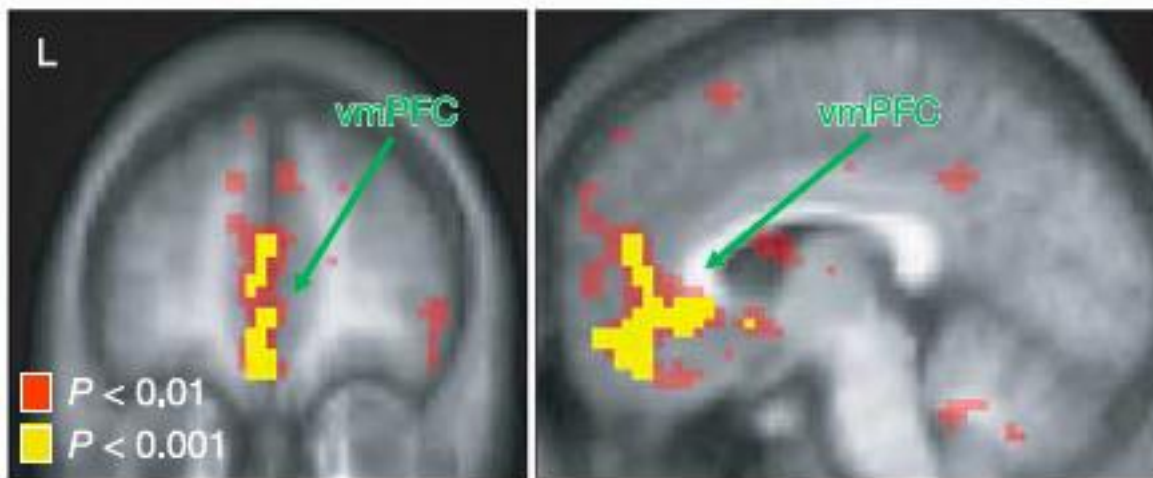
FOUR-ARM BANDIT



The mean reward also varies over time, enabling an assessment of exploration/exploitation

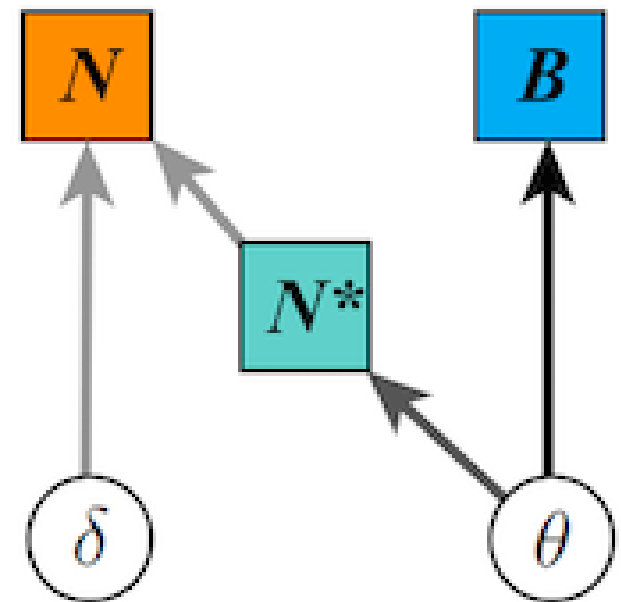
RESULTS – NEURAL DATA

- The model provides a value for the probability of each choice in the task.
- One can correlate these predicted probabilities for the chosen option with the neural data
- Found significant correlations in vmPFC
- Negatively correlated with a small area in dlPFC



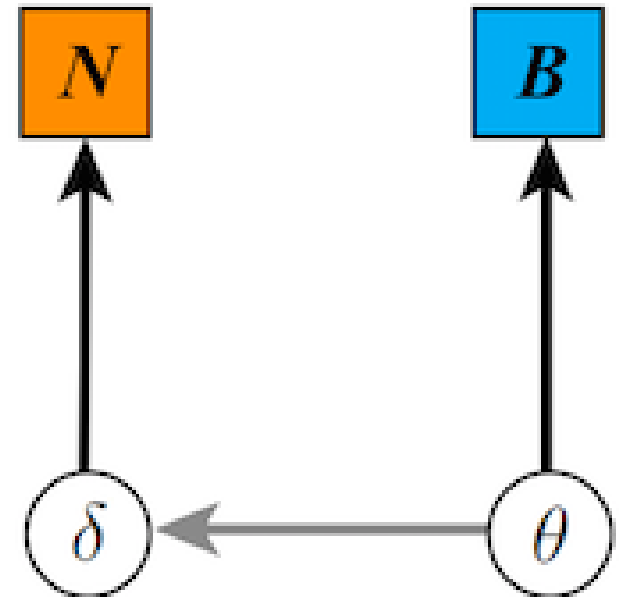
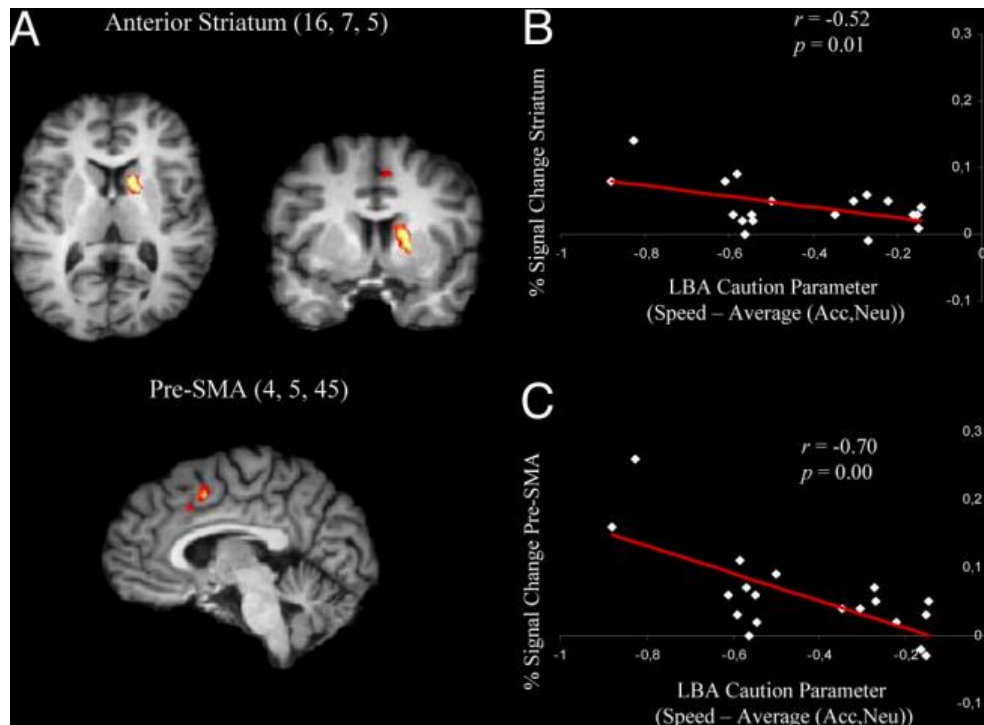
MODEL DECODING

- You can imagine using different models to gather different 'internal states' (θ)
- Then, drawing comparisons across models by how well the neural data are predicted by the models' internal state
- This is exactly what Mack et al. (2013) did for the GCM and prototype models



TWO-STAGE NEURAL

- Process of analyzing two streams of data independently, and then determining which aspects of the data are related



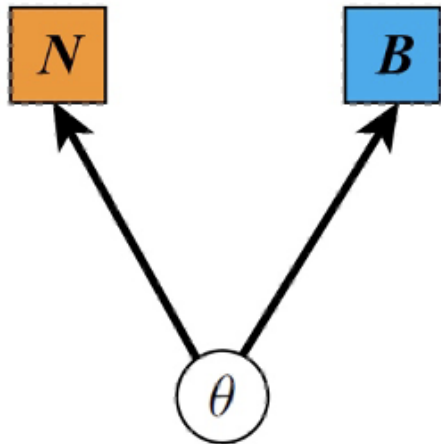
SIMULTANEOUS MODELING

- **Previous approaches make some assumptions about which aspect of the data is the ‘governing force’**
- **These are unidirectional constraints, and from Love (2015), we get the sense that this may not be the best choice**
- **Can we consider both variables as equally constraining?**
- **Concerns discriminative versus generative modeling goals**

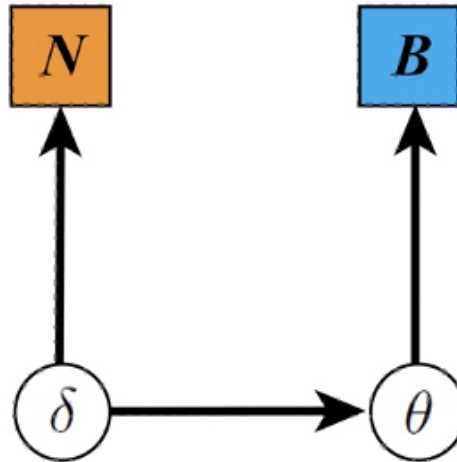
SIMULTANEOUS MODELING

- Here are some examples:

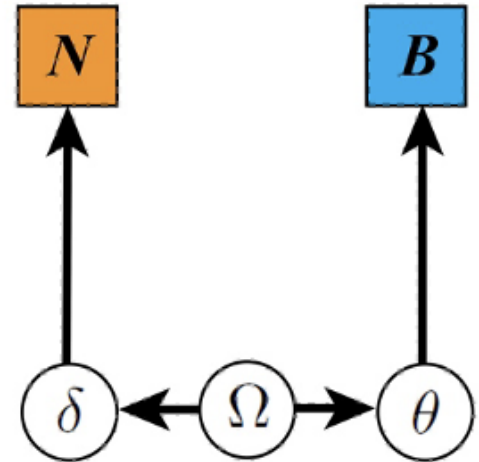
Joint (Simultaneous) Modeling



Integrative



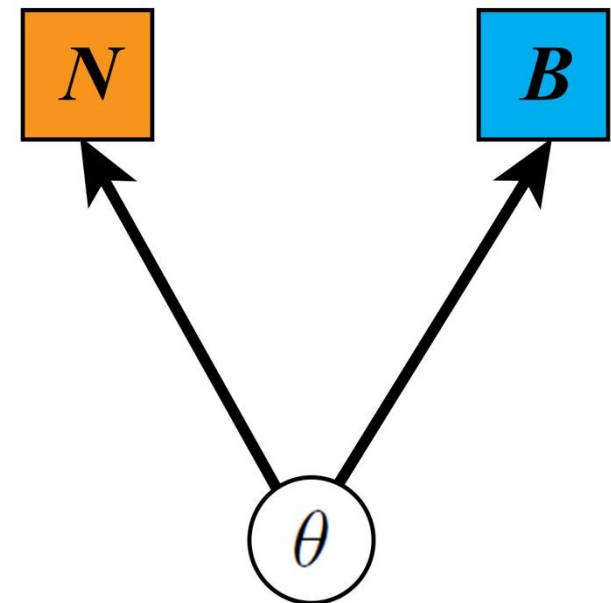
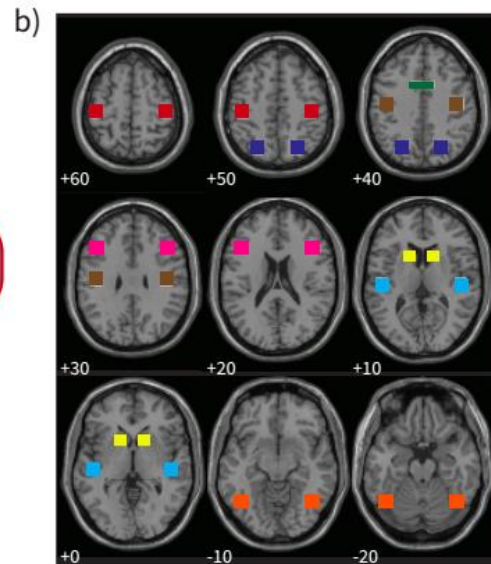
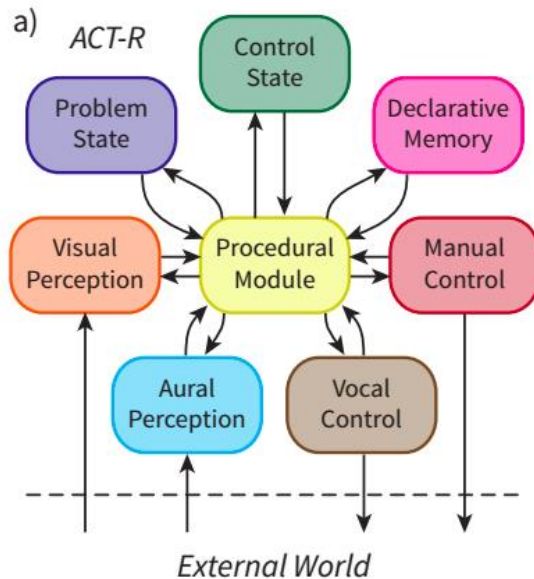
Directed



Hierarchical

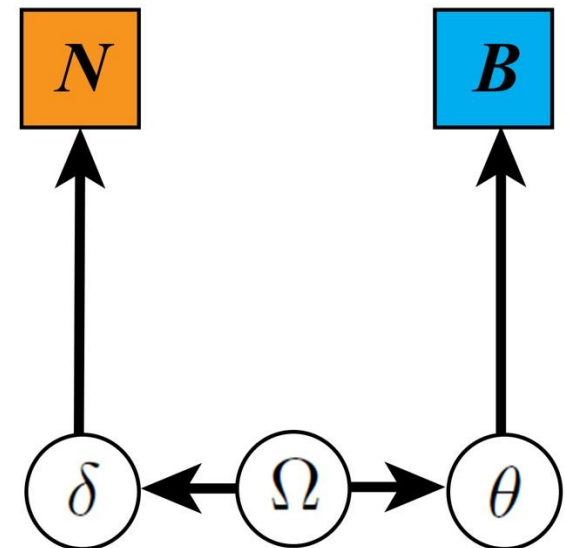
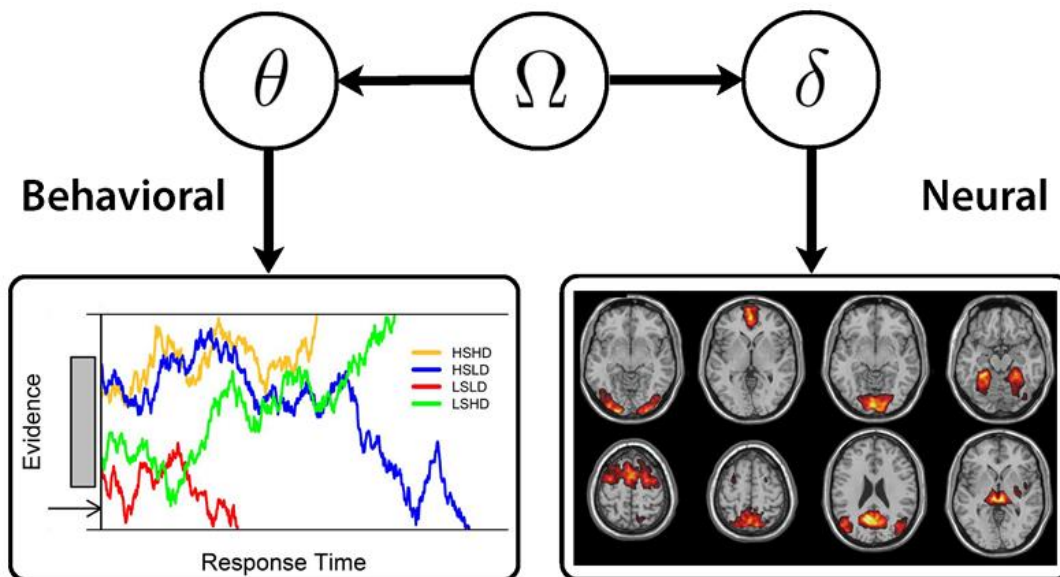
INTEGRATIVE

- Architecture that forces one core model to generate predictions for both behavioral and neural data
 - ACT-R



JOINT MODELING

- Assuming two 'submodels' for each data modality
- Define a hyperstructure for connecting them
 - Neural DDM



COMPARING THE APPROACHES

- It would be nice to have some way to compare these approaches so that we know which one to use for a given application.
- How should the various approaches be evaluated?
- Along what dimensions should they be compared and contrasted?
- Do these approaches cover all possible types of linkage between neural and behavioral measures?

COMPARING THE APPROACHES

One proposal is to use the following metrics:

1. Number of stages: how many steps are needed?
2. Commitment to a particular theory: how flexible is the modeling approach to new data types or new models?
3. Type of information flow: how do the random variables influence, and are influenced by, other sources of random variation?
4. Difficulty of implementation: practically speaking, how hard is this to recreate?
5. Type of exploration: Is this approach good for exploration or confirmation of theory?

Factor	Theoretical	Two-stage	Direct Input	Latent Input	Joint Modeling	Integrative
Number of stages	{2, 3, ...}	{ 2, 3 }	1	{ 2, 3 }	1	1
Commitment to a particular theory	None	Weak	Medium	Weak	Weak	Strong
Type of information flow	Conceptual	One-way	One-way	One-way	Two-way	Two-way
Difficulty of implementation	High	Low	Medium	Medium	High	High
Type of exploration	Exploratory	Exploratory	Confirmatory	Either	Either	Confirmatory

CONCLUSIONS

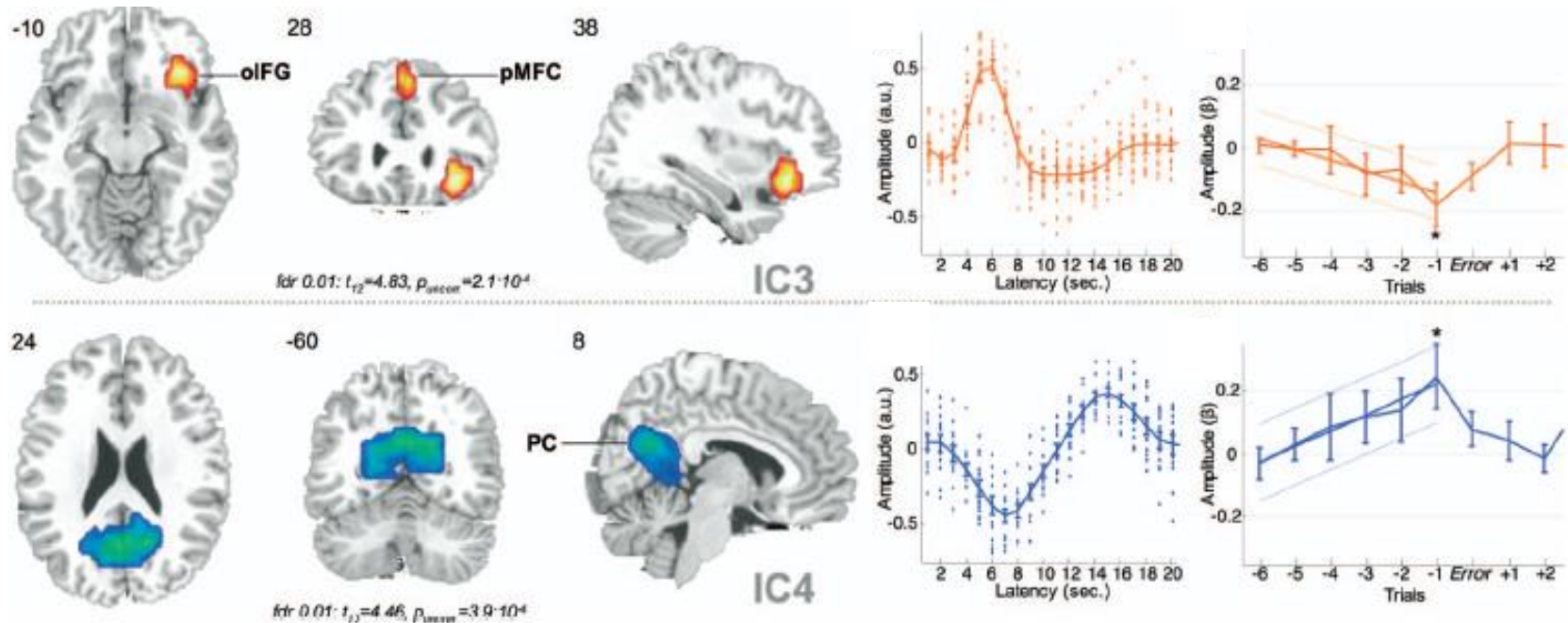
- **There are many ways to inform cognitive models with neural data**
- **There are also many ways to inform our analysis of neural data with cognitive models**
- **New approaches just waiting to be developed**
- **Powerful new results just waiting to be discovered by the inclusion of data that have not been previously considered**

SBI SUMMER SCHOOL: JOINT MODELING: FMRI

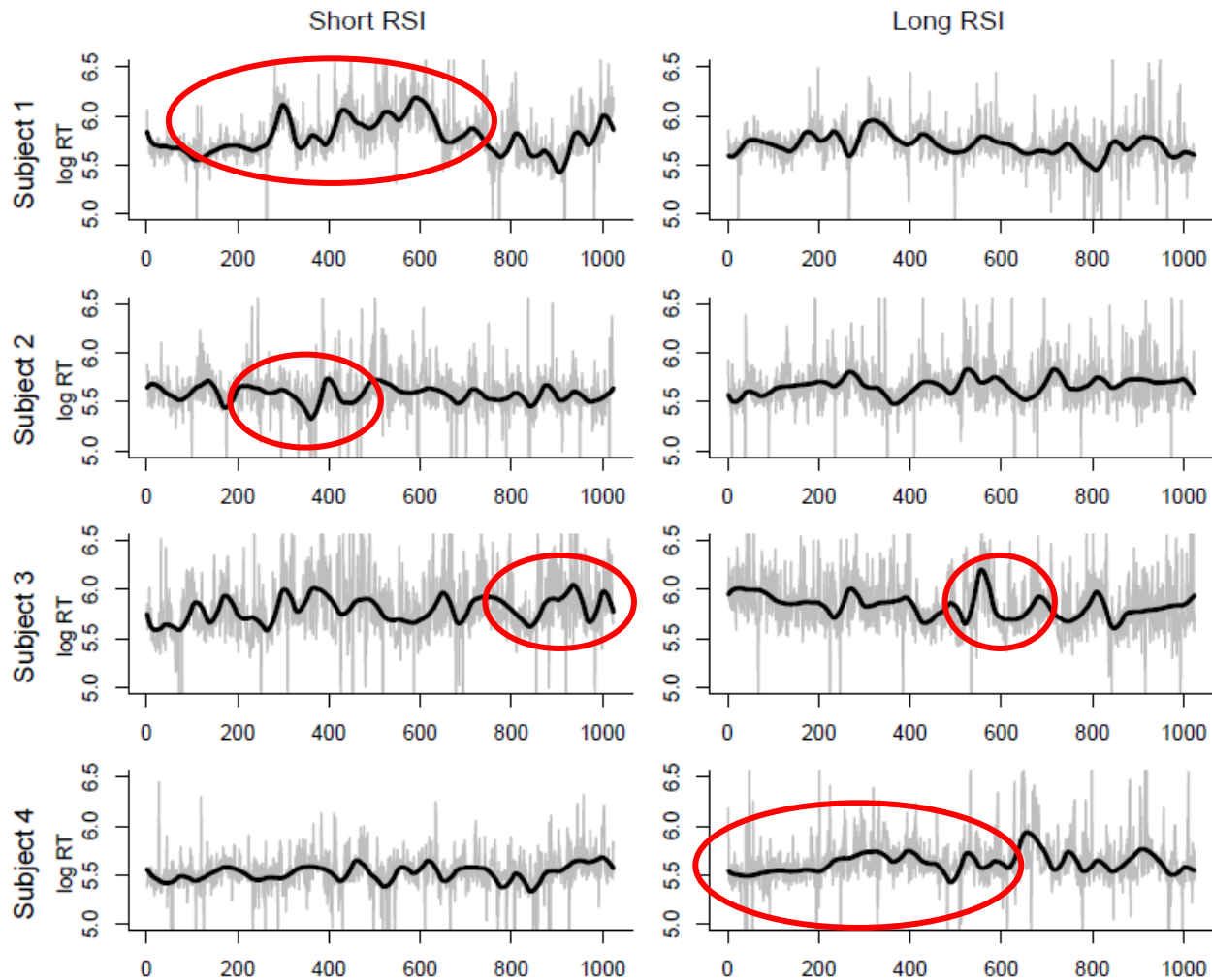


The Wandering Mind

- Default mode network is a set of brain regions that are active when an individual is “off task”

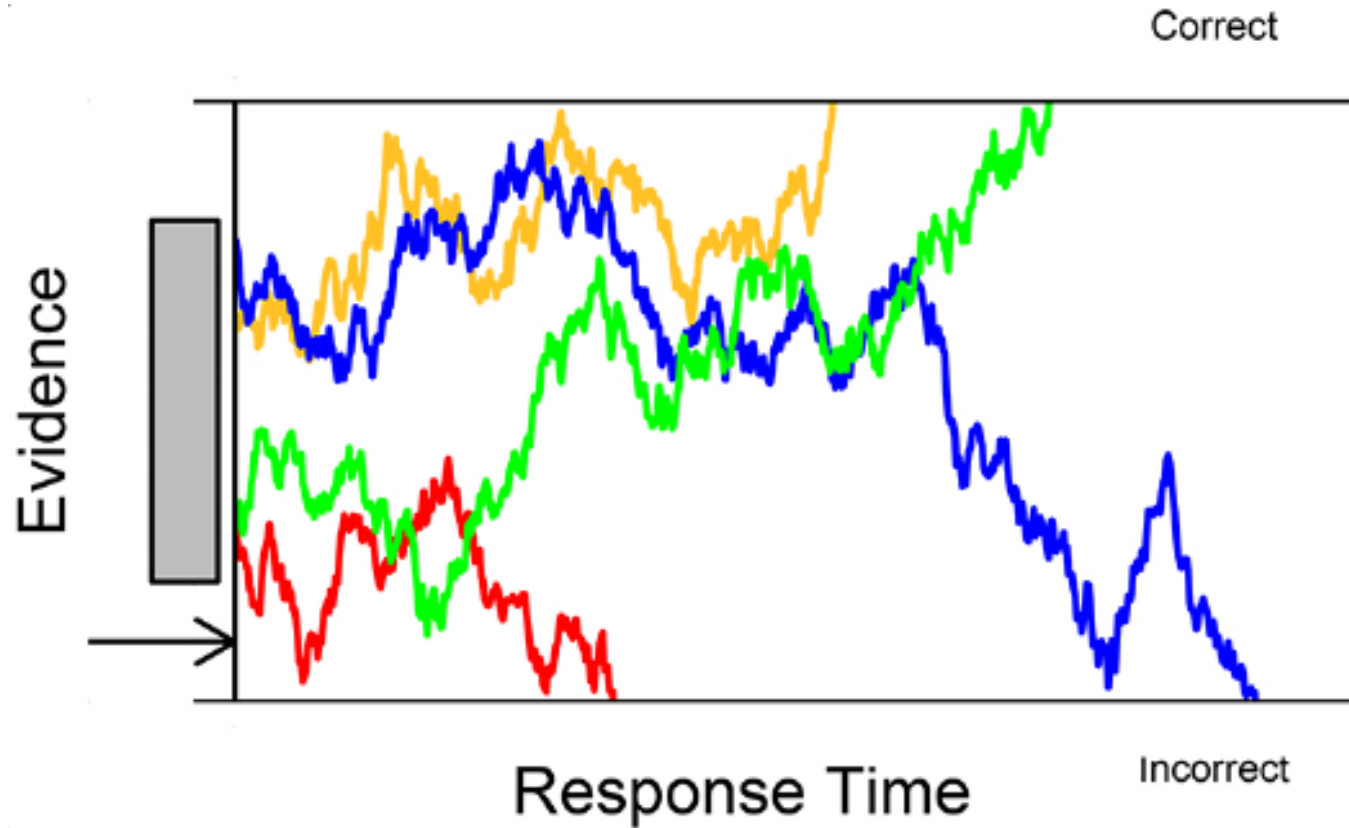


Behavioral Data

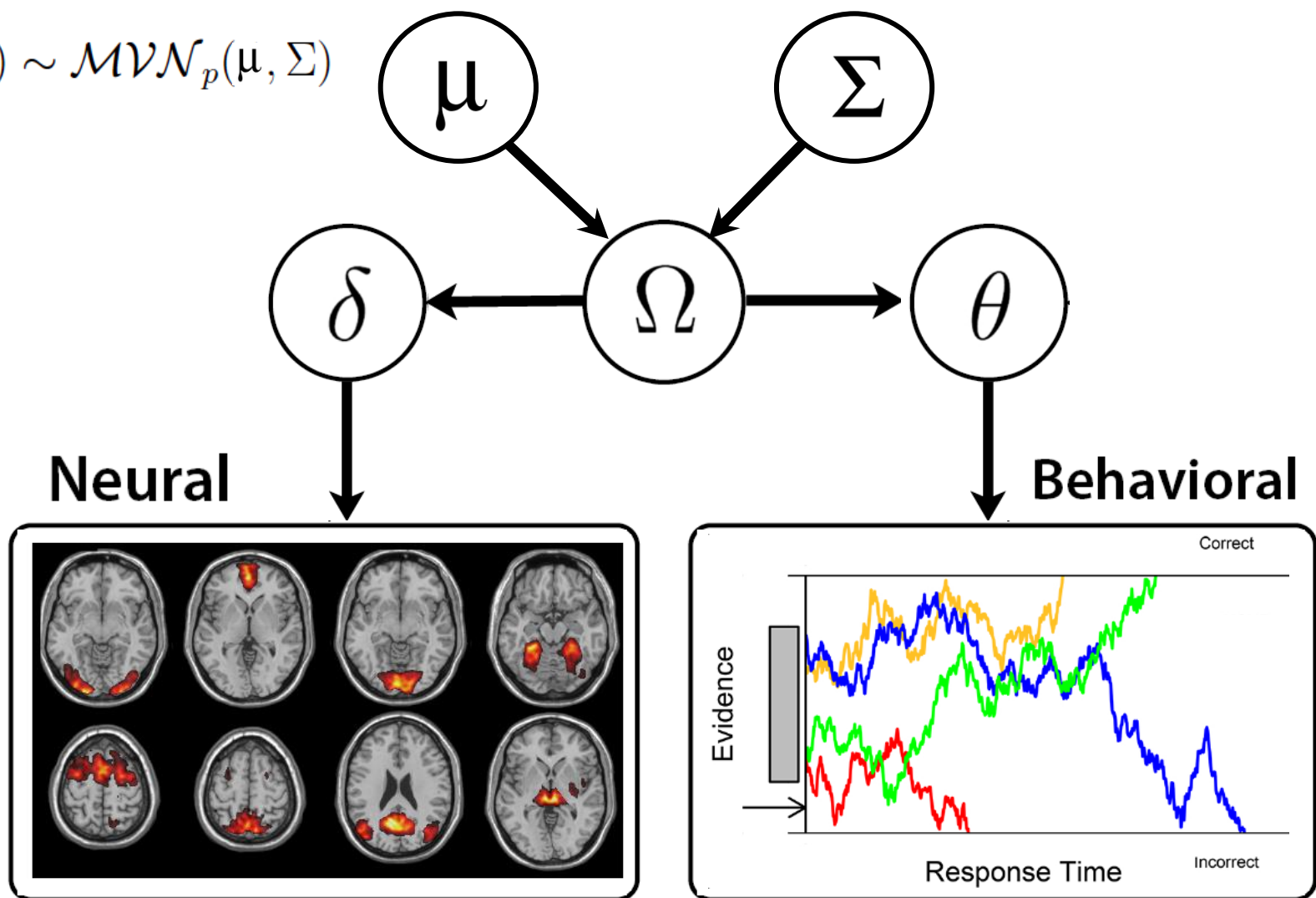


(Craigmile et al., 2013)

Diffusion Decision Model



$$(\theta_j, \delta_j) \sim \mathcal{MVN}_p(\mu, \Sigma)$$



- Trial-level parameters for bias and drift rate
- Trial-level parameters for degree of source activation
- Subject-level parameters for neural/behavioral constraint

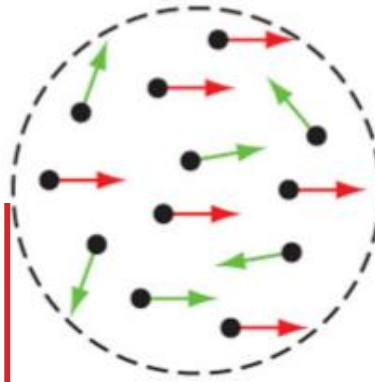
EXPERIMENT

Pre-stimulus Scan



8 s

Stimulus Onset



(Free Response)

Behavioral Response

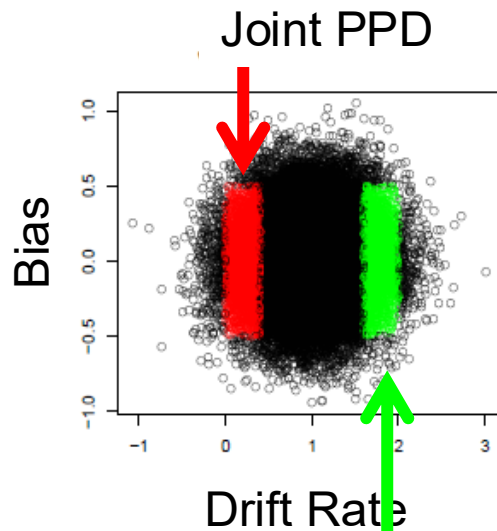


Choice RT

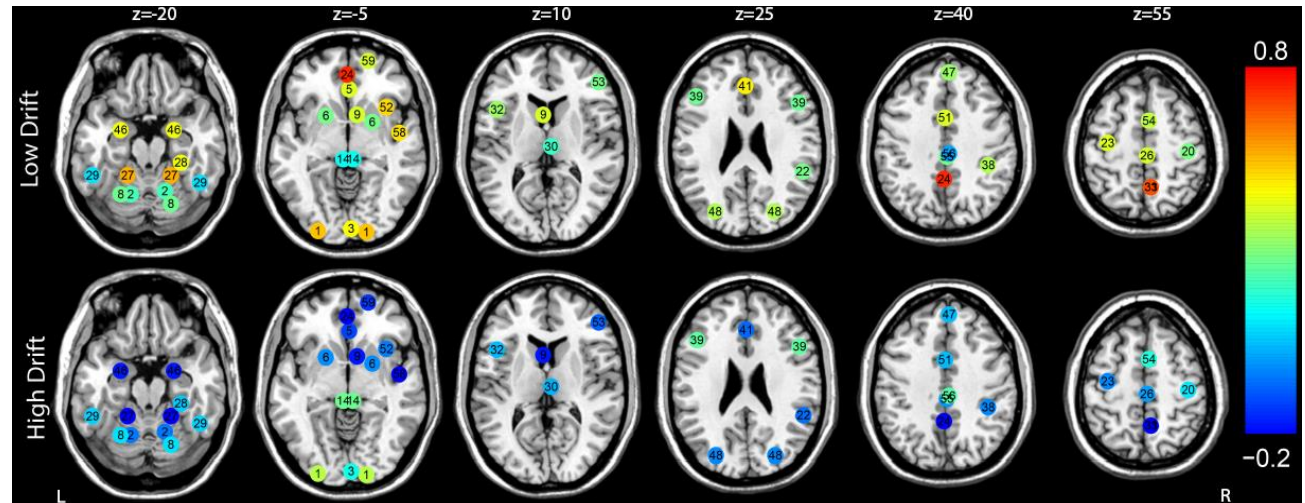
Time

MECHANISTIC INTERPRETATION

Slow, error-prone process



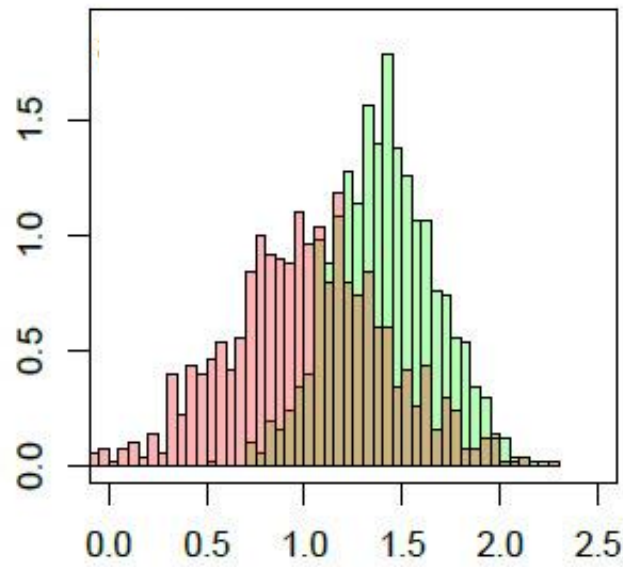
Fast, accurate process



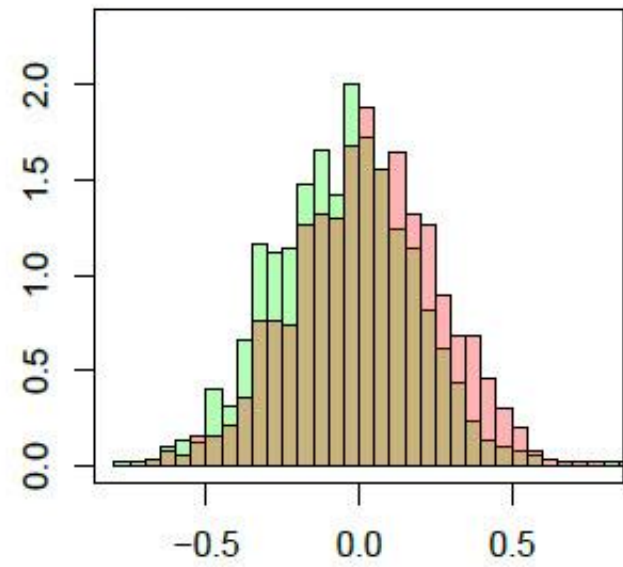
Example: Test Trial 82

● NDDM
● DDM

Density



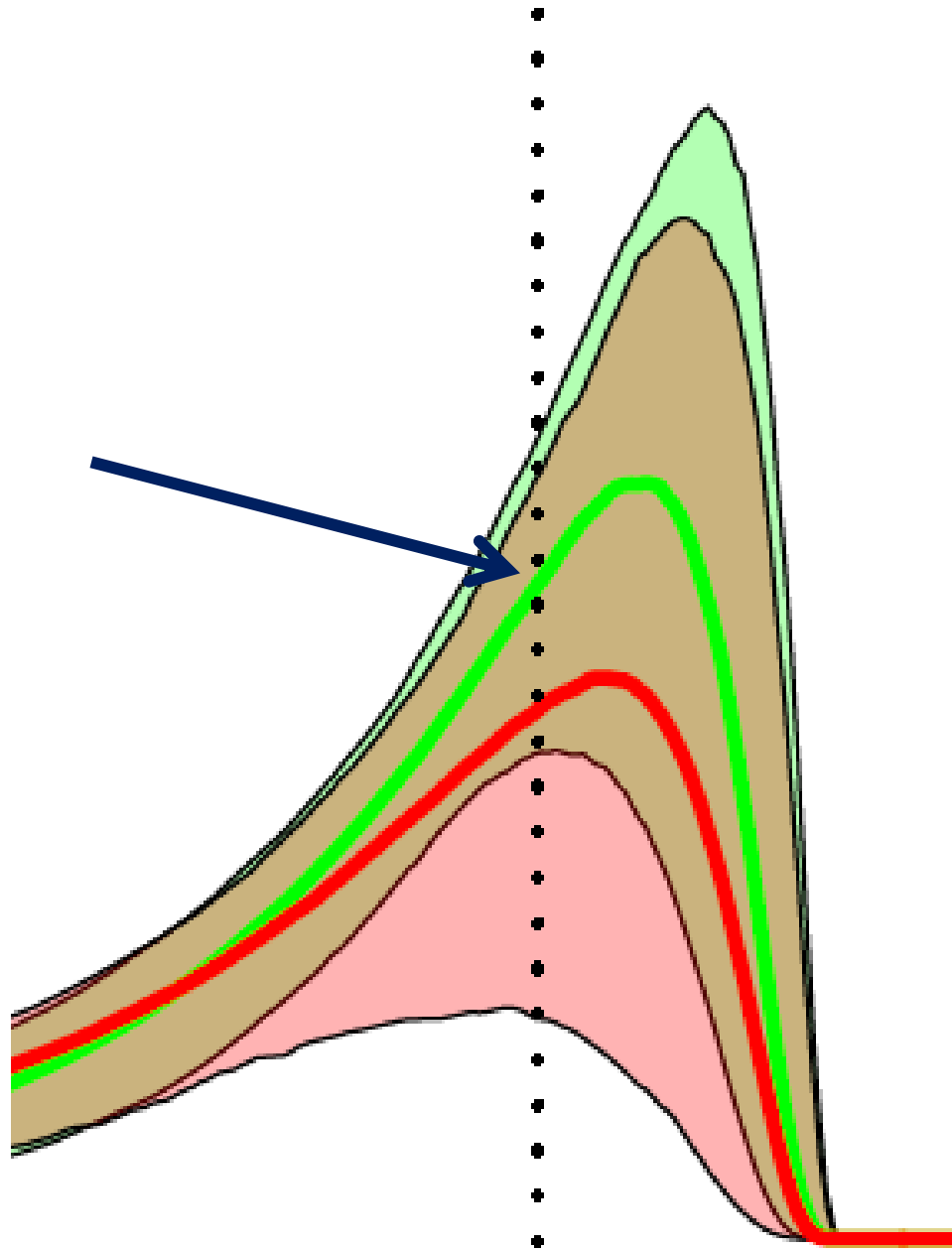
Drift rate



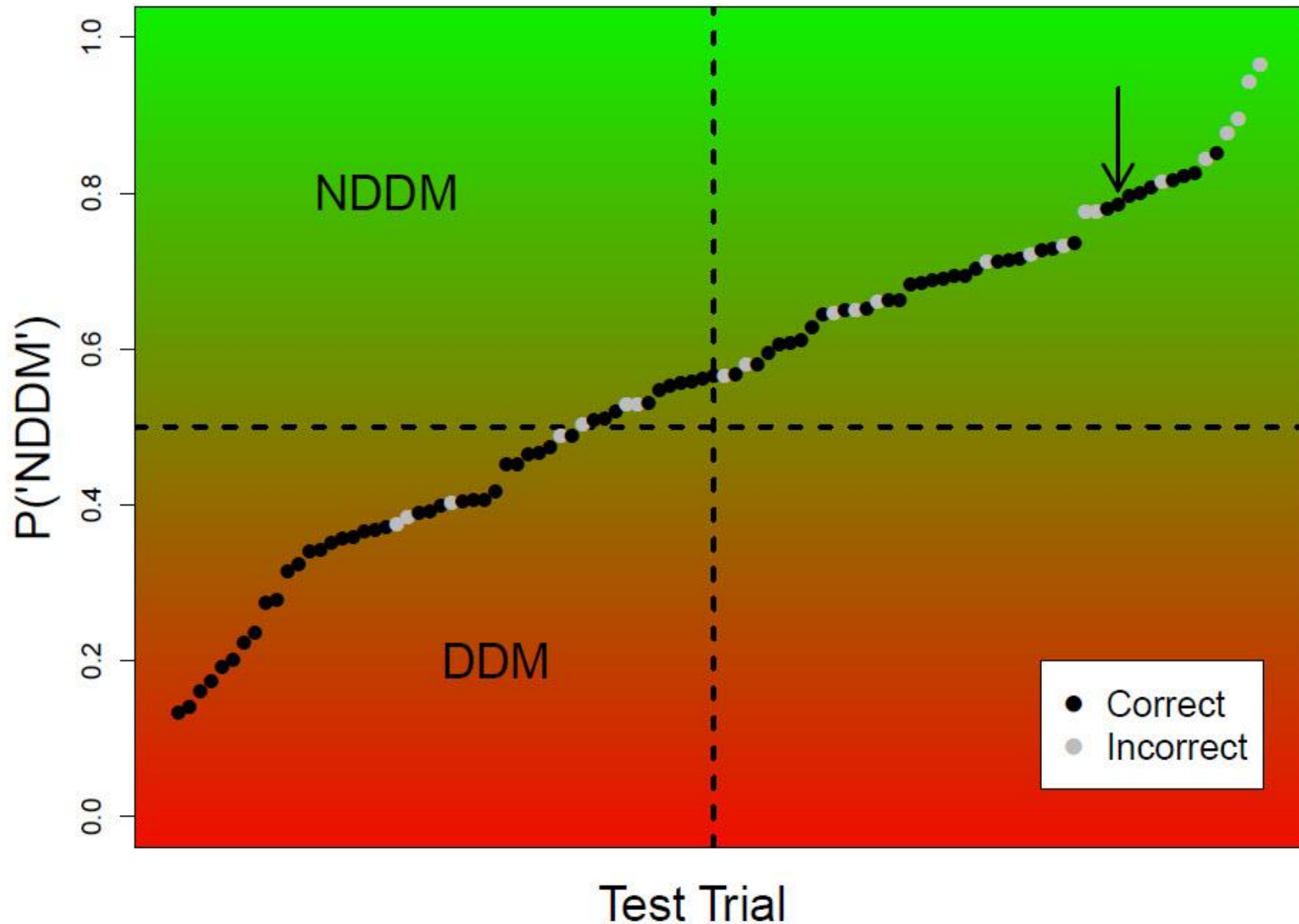
Bias

Example:
Test Trial 82

● NDDM
● DDM

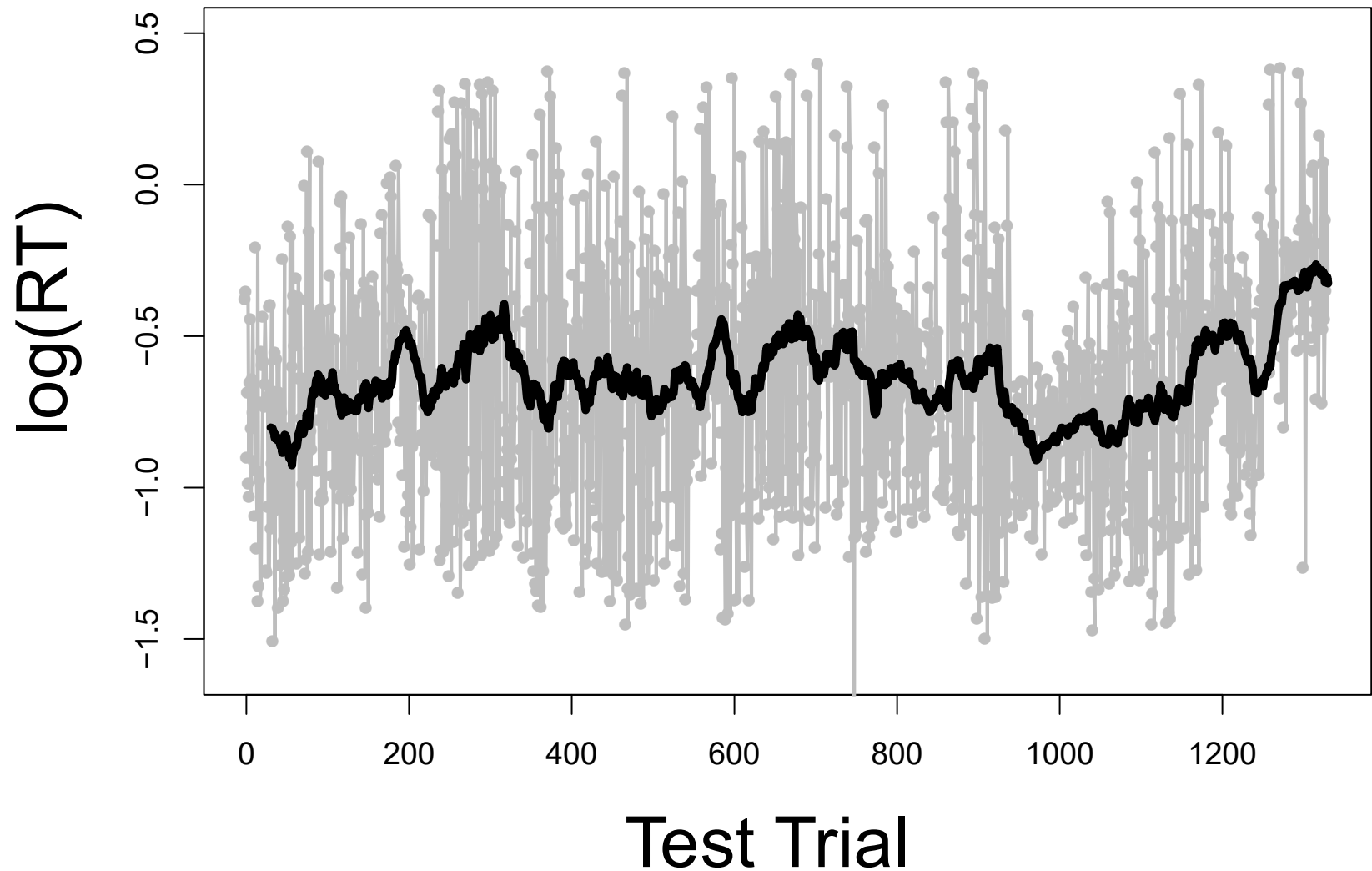


CROSS-VALIDATION TEST



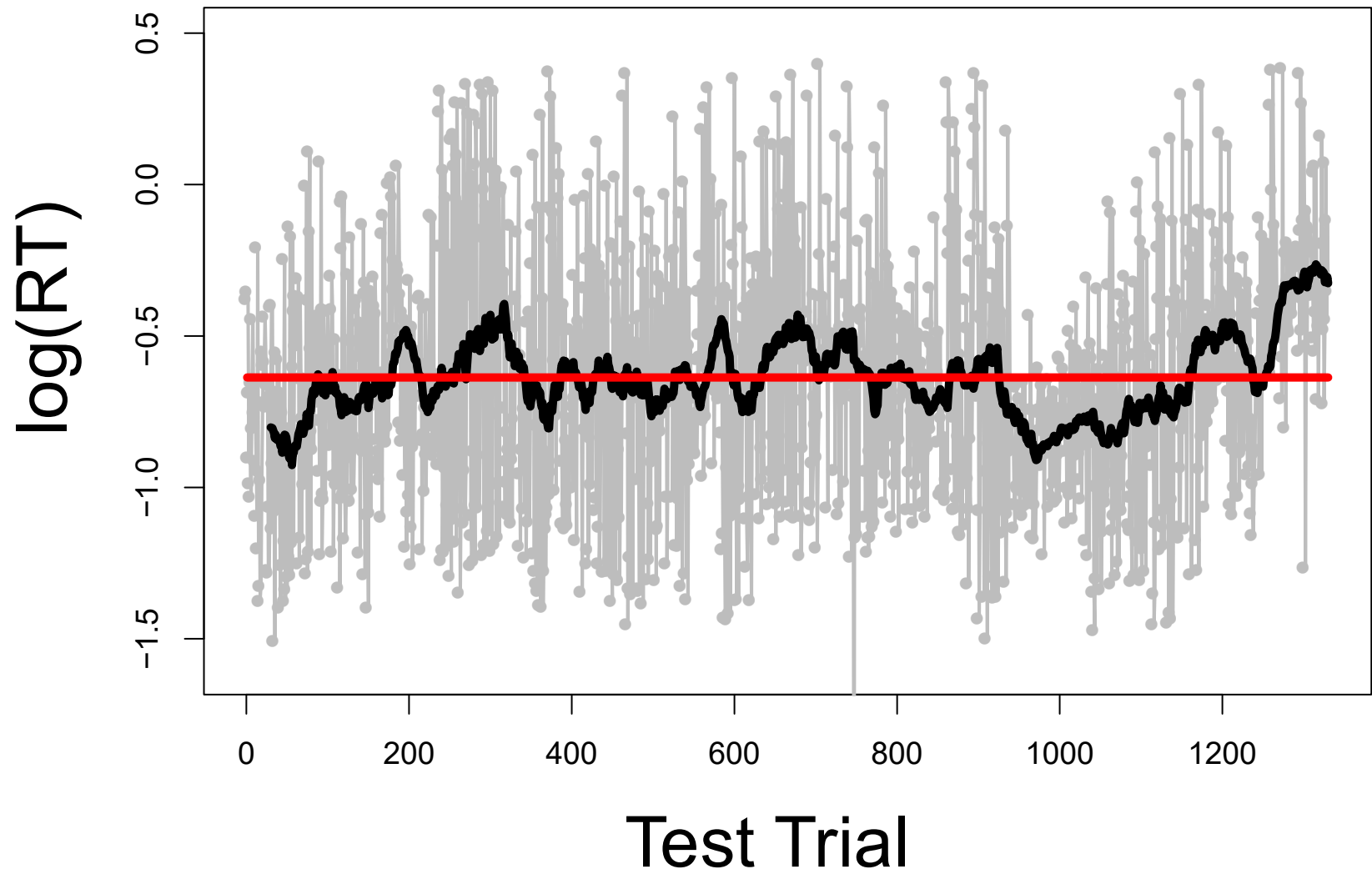
Time Series

- Data, Raw
- Data, Smoothed
- DDM (no neural data)
- NDDM (neural covariate)



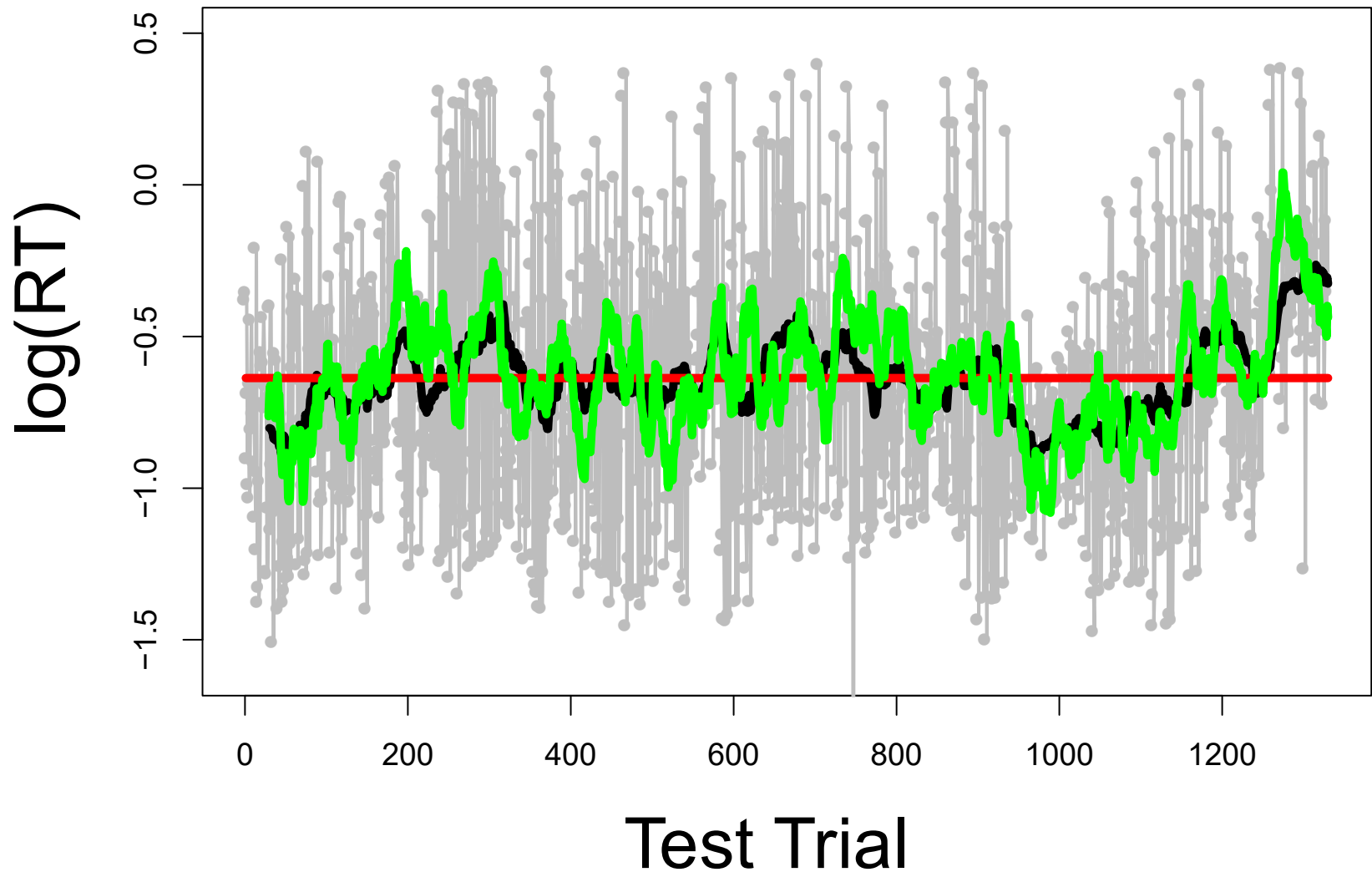
Time Series

- Data, Raw
- Data, Smoothed
- DDM (no neural data)
- NDDM (neural covariate)



Time Series

- Data, Raw
- Data, Smoothed
- DDM (no neural data)
- NDDM (neural covariate)



Linking Function

$$(\theta_j, \delta_j) \sim \mathcal{MVN}_p(\mu, \Sigma)$$

- We can decompose Σ into a system of three matrices:

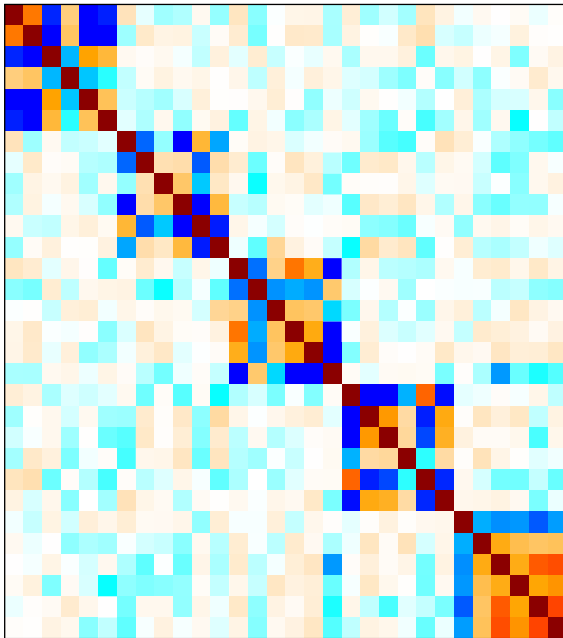
$$\Sigma = \Lambda \Phi \Lambda^\top + \Psi$$

The diagram illustrates the decomposition of the covariance matrix Σ into three matrices: Λ , Φ , and Ψ . Σ is a 10x10 matrix with a complex pattern of blue, cyan, yellow, and red cells. It is equal to the product of Λ (a 10x5 matrix with black and white cells), Φ (a 5x5 matrix with a few colored cells), and $\Lambda^\top$ (a 5x10 matrix with a complex pattern of colored cells), plus Ψ (a 10x10 matrix with a sparse pattern of blue and green cells along the diagonal).

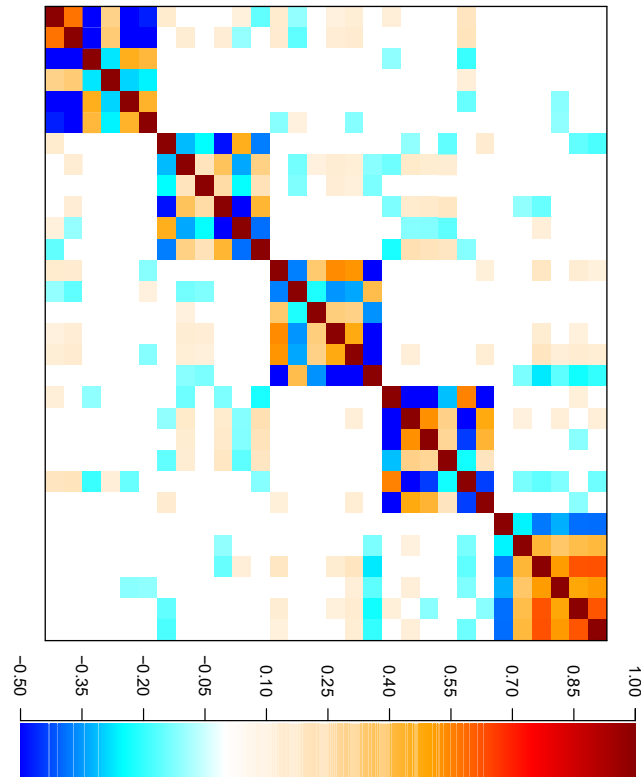
Linking Function

$$(\theta_j, \delta_j) \sim \mathcal{MVN}_p(\mu, \Sigma)$$

Covariance



FA NDDM



Linking Function



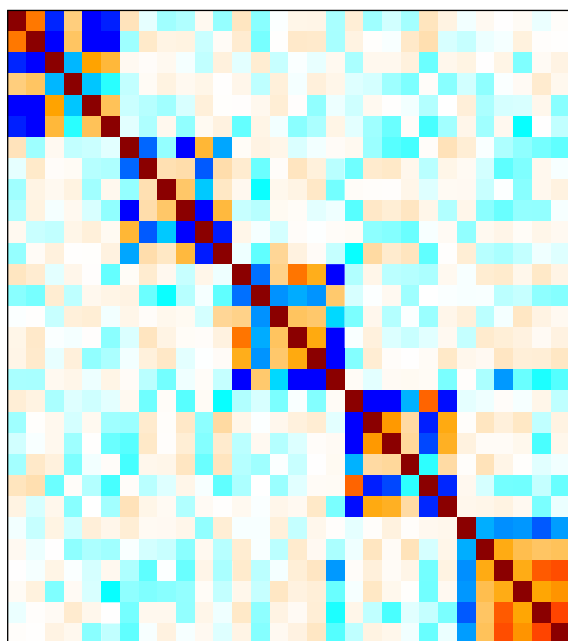
Inhan Kang



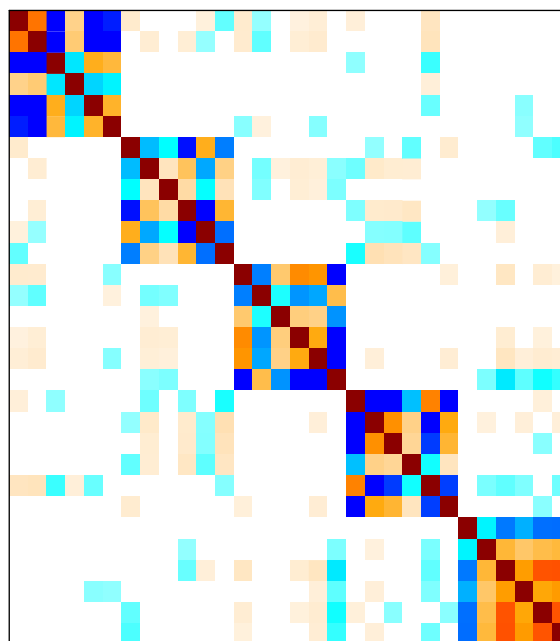
Woojong Yi

$$(\theta_j, \delta_j) \sim \mathcal{MVN}_p(\mu, \Sigma)$$

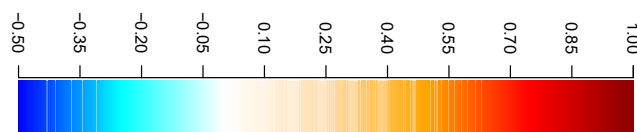
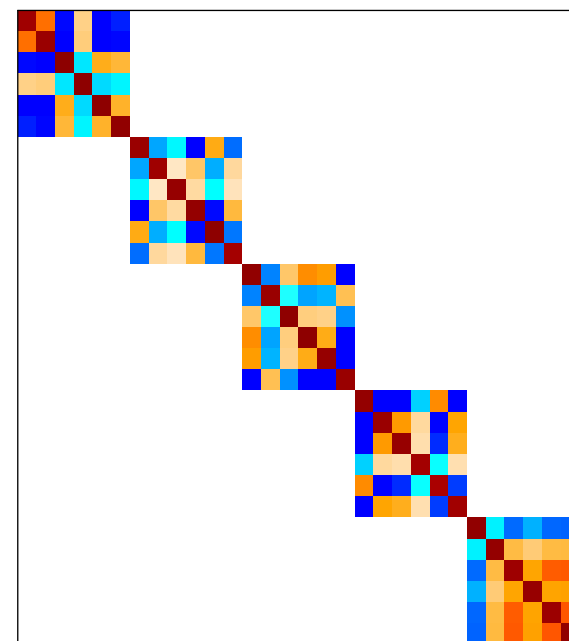
Covariance



FA NDDM

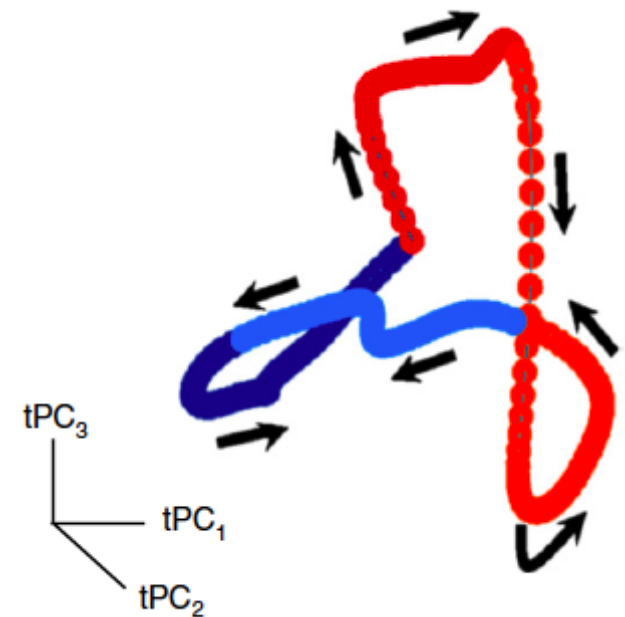
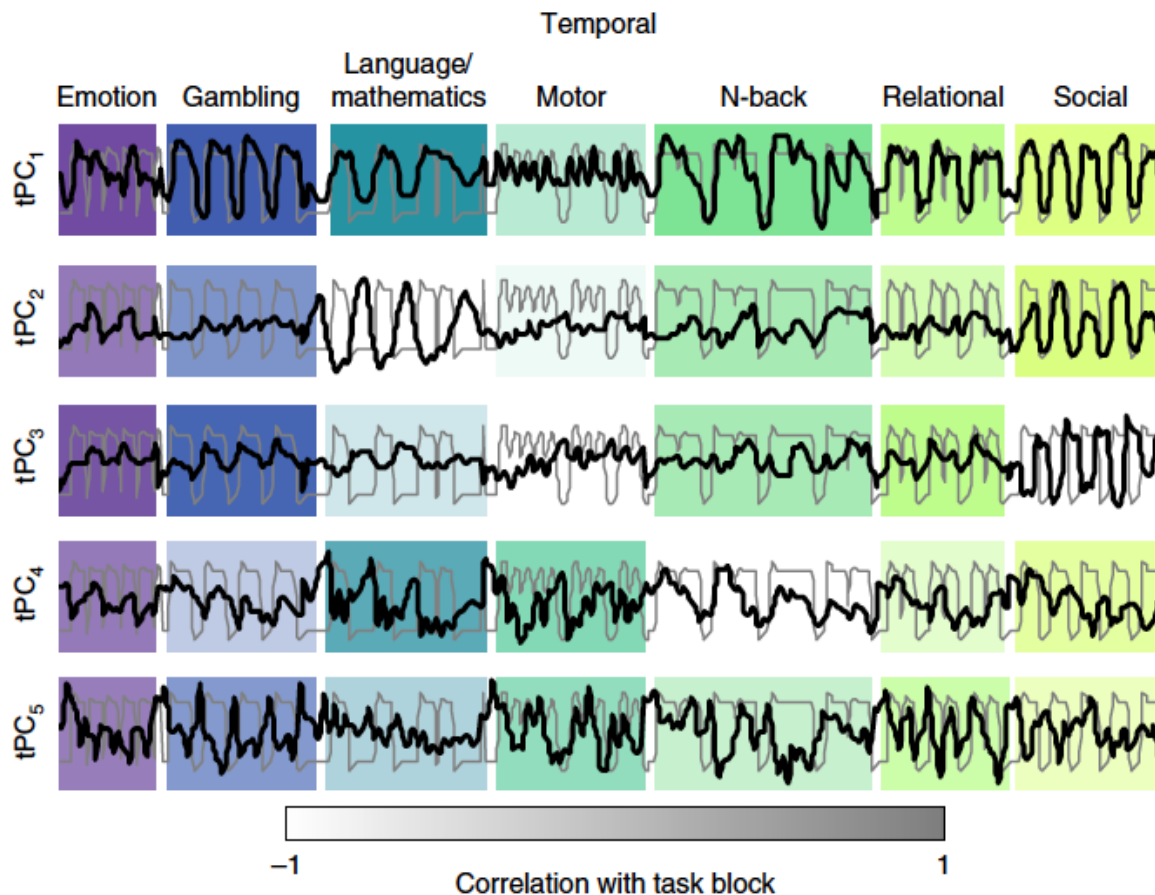


Lasso FA NDDM



(Kang, Yi, Turner, 2021)

Latent Dynamics



Gaussian Process Joint Modeling



Giwon Bahg

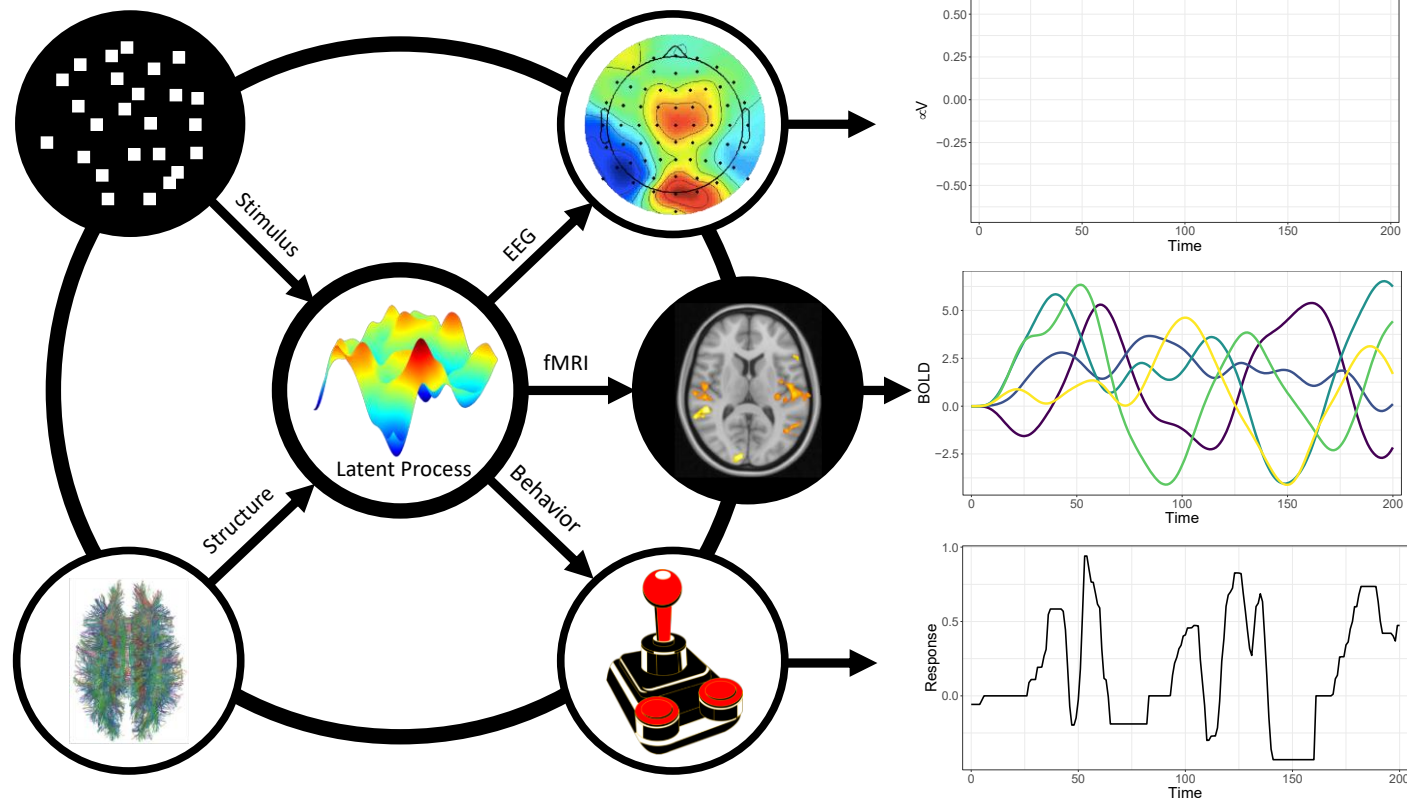


Dan Evans



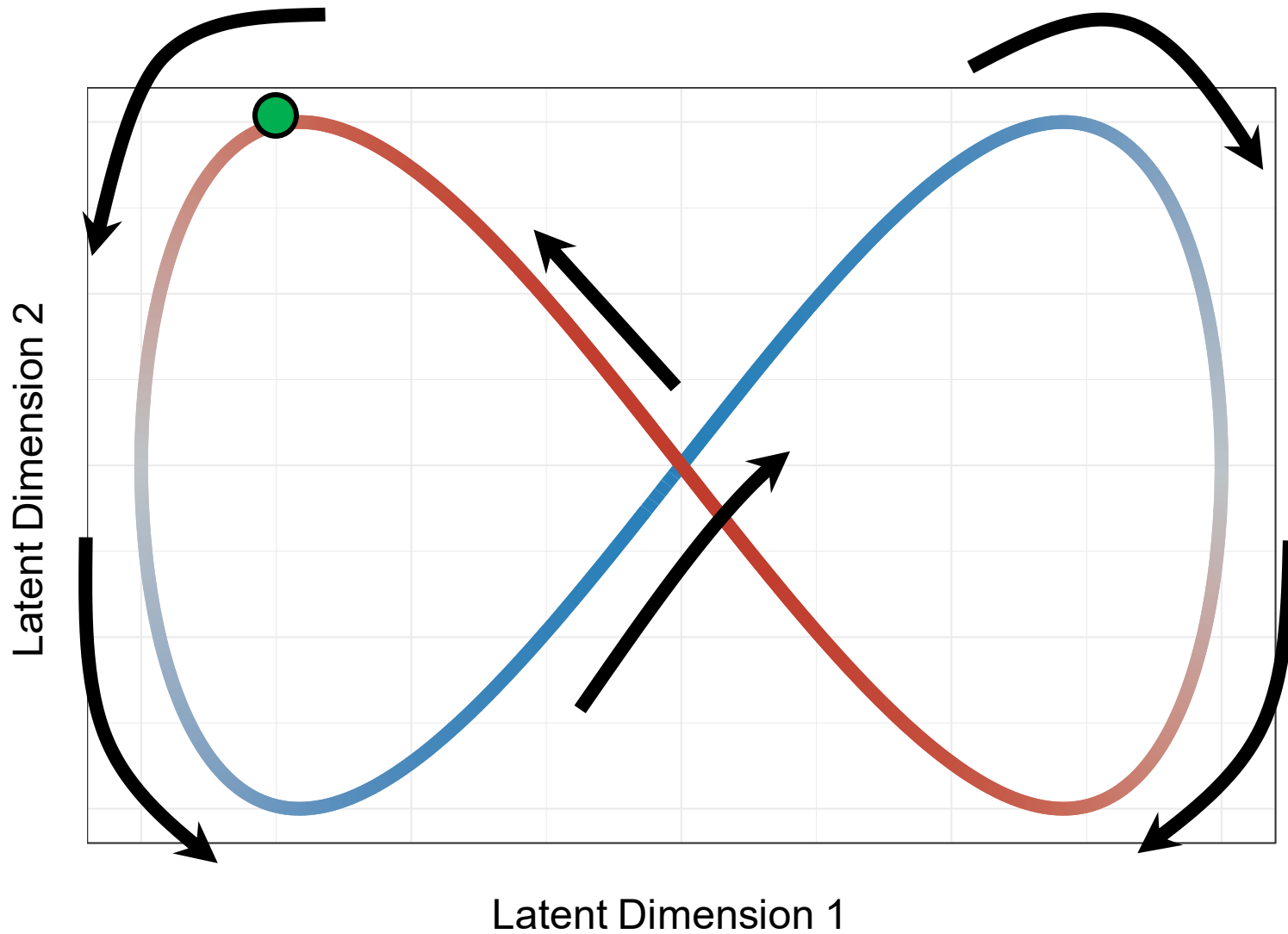
Mathew Galdo

- We developed GPJM to deal with nonlinearities on a moment-by-moment basis

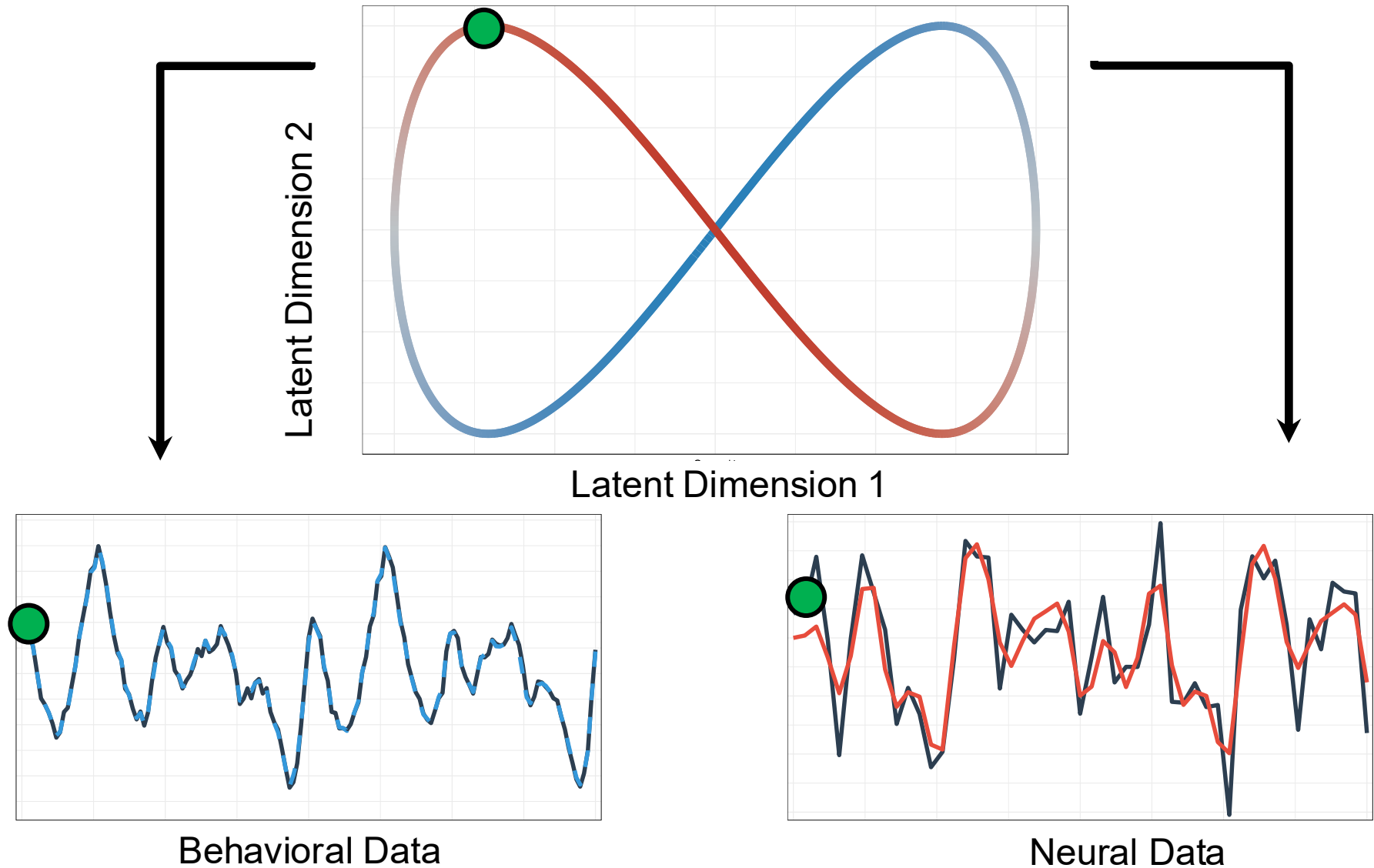


(Bahg et al., 2020)

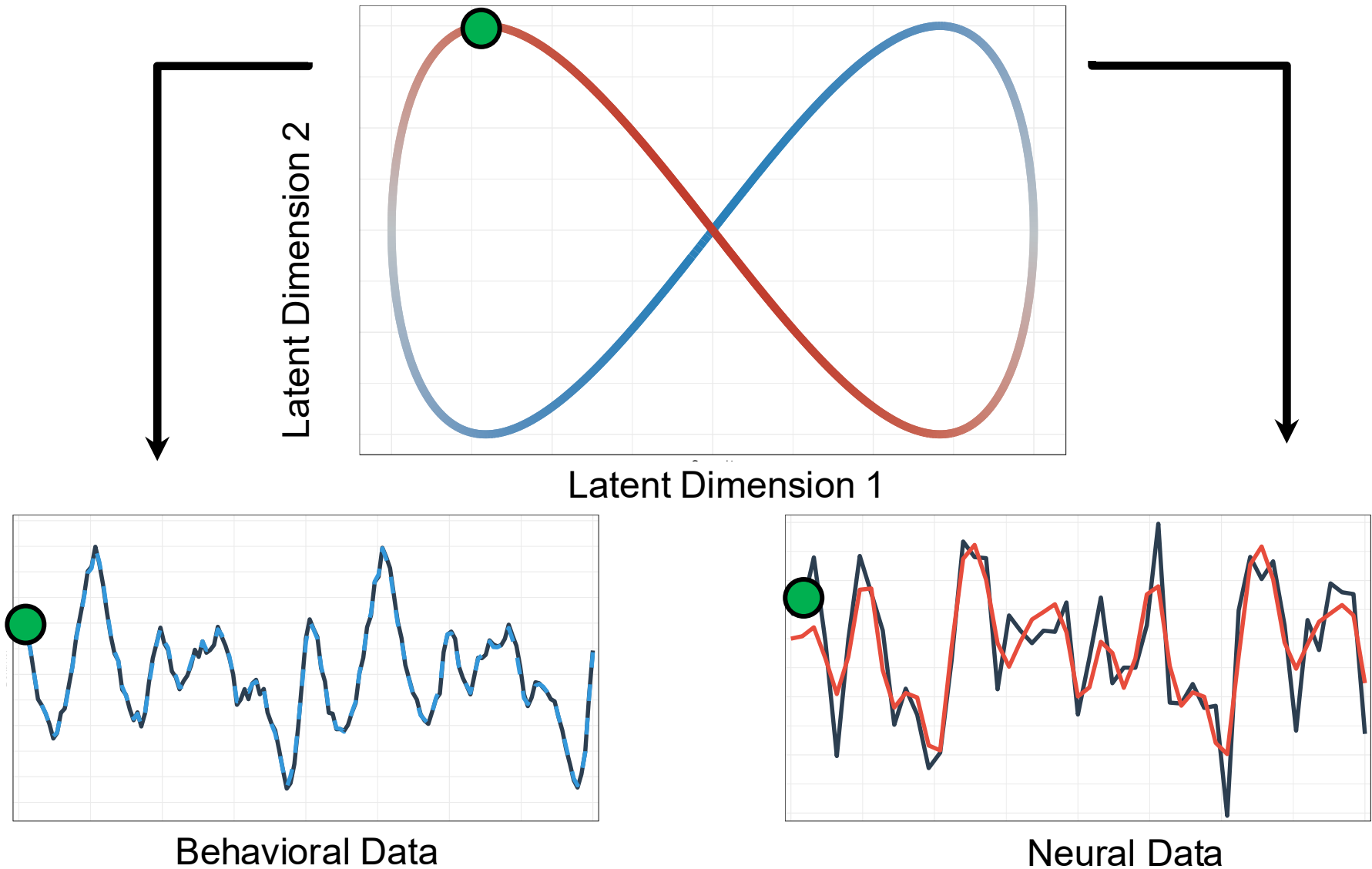
Latent Dynamics



Latent Dynamics



Latent Dynamics



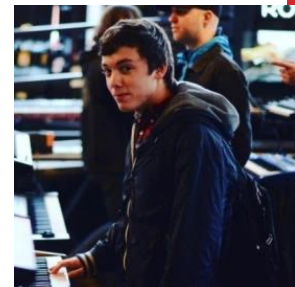
Gaussian Process Joint Modeling



Giwon Bahg



Dan Evans



Mathew Galdo

Latent
Hyperstructure:

$$X \sim \mathcal{N}(\mathbf{0}, K_{tt})$$

$$K_{tt} = [k_t(t_i, t_j)]_{ij} := \left[s_t^2 \exp \left(- \frac{(t_i - t_j)^2}{2l_t^2} \right) \right]_{ij}$$

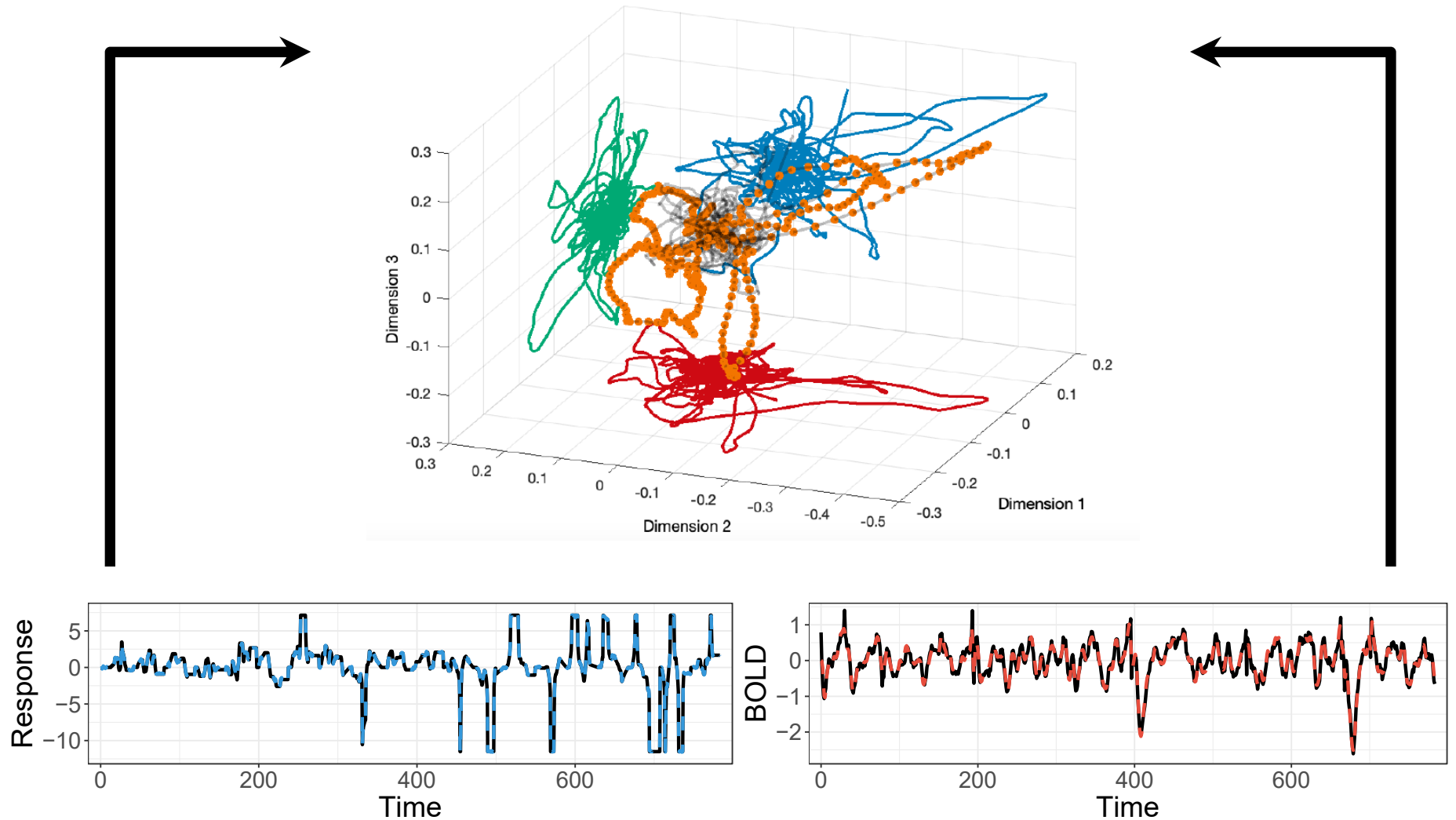
Neural
Submodel:

$$Y_N \sim \mathcal{N}(\mathbf{0}, K_{XX(N)} + \sigma_N^2 I)$$
$$K_{XX(N)} = [k_N(x_i, x_j)]_{ij} := \left[s_N^2 \exp \left(- \frac{(x_i - x_j)^2}{2l_N^2} \right) \right]_{ij}$$

Behavioral
Submodel:

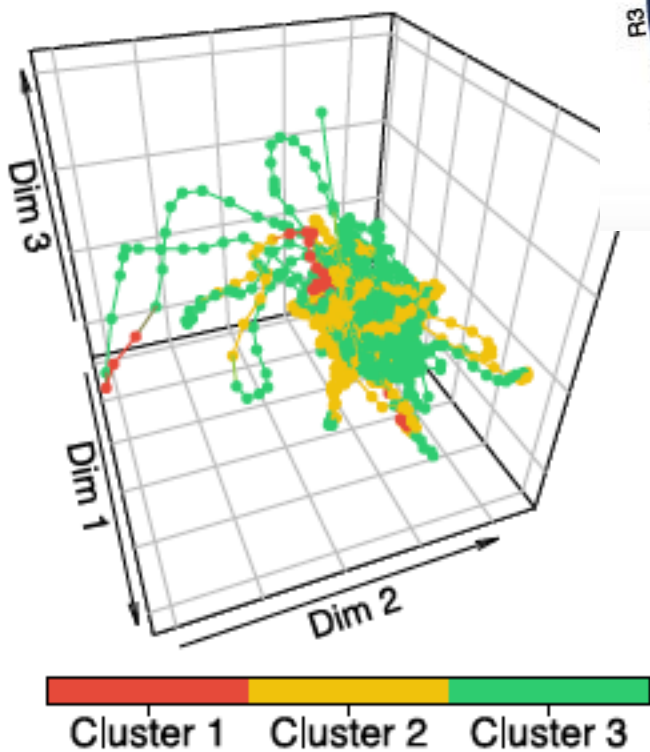
$$Y_B \sim \mathcal{N}(\mathbf{0}, K_{XX(B)} + \sigma_B^2 I)$$
$$K_{XX(B)} = [k_B(x_i, x_j)]_{ij} := \left[s_B^2 \exp \left(- \frac{\|x_i - x_j\|}{l_B} \right) \right]_{ij}$$

Application: Motion Tracking Task

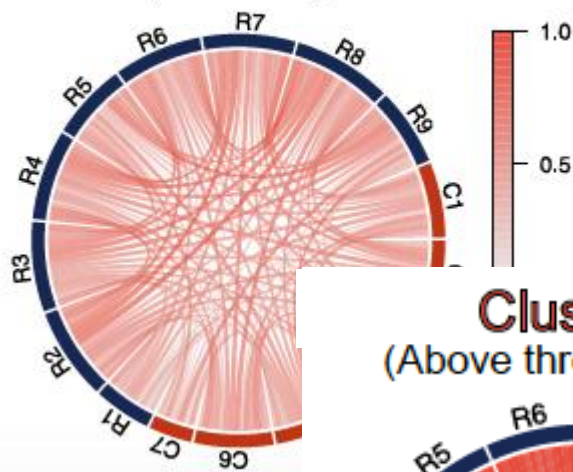


(Bahg et al., 2020)

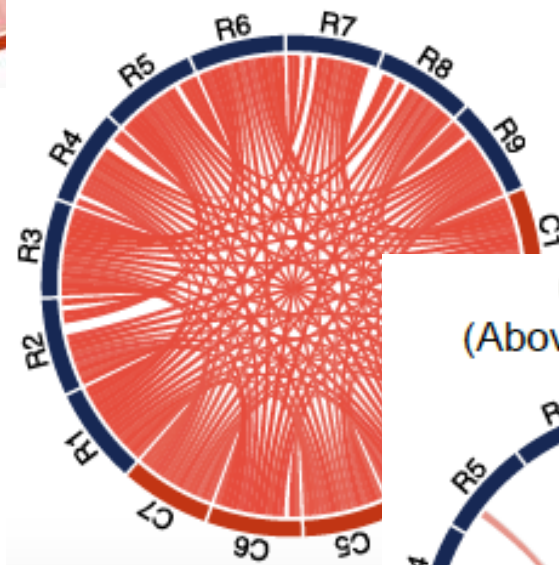
Functional Coactivation



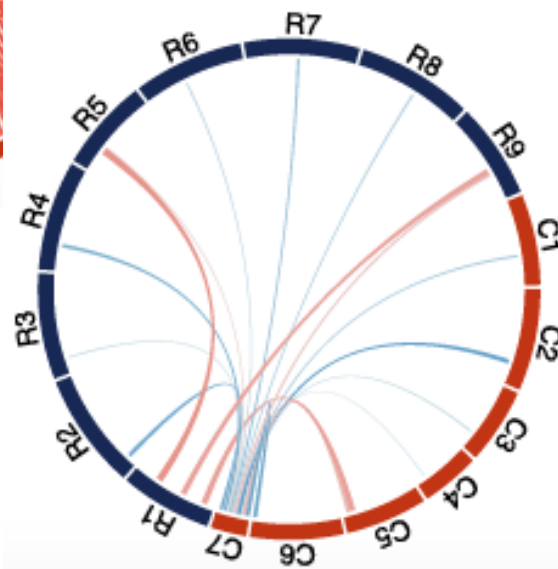
Cluster 3
(Reference)



Cluster 1
(Above threshold only)



Cluster 2
(Above threshold only)



Conclusions

- The impetus for linking brain and behavioral data should be the one thing they have in common: the mind
- By abstracting mental operations into a shared latent space, we are better postured to exploit statistical commonalities within any measure of cognition
- Joint modeling is one convenient way to do this

